

Supplement

A Hybrid Deep Learning and Statistical Approach for Fault Detection and Diagnosis in AGRU Systems: Integration with Aspen Plus and Explainable AI

Nadia Khan¹, Syed Ali Ammar Taqvi^{2*}, Maria Waqas³

¹ Department of Polymer and Petrochemical Engineering, Faculty of Chemical and Process Engineering, NED University of Engineering and Technology, University Road, 75270 Karachi, Pakistan

² Department of Chemical Engineering, Faculty of Chemical and Process Engineering, NED University of Engineering and Technology, University Road, 75270 Karachi, Pakistan

³ Department of Computer and Information Systems Engineering, Faculty of Electrical and Computer Engineering, NED University of Engineering and Technology, University Road, 75270 Karachi, Pakistan

* Corresponding author, e-mail: aliammar@neduet.edu.pk

Algorithm S1 Hybrid fault detection and diagnosis algorithm

Step 1: Generate fault and fault-free datasets using Aspen Plus for fault analysis.

Step 2: Split the dataset based on selected features (x_1 to x_{18}) and fault labels (F_1 to F_6).

Step 3: Data preprocessing involves normalizing the dataset.

Step 4: Built an LSTM AE/PCA model to detect the fault using the following steps

Divide the normalized data into normal and fault data sets.

Define the threshold of RE, T^2 , and SPE using a normal data set.

In the PCA space model, calculate the T^2 and SPE values using the faulty dataset.

In the LSTM AE model, calculate RE values using the faulty dataset.

Faults are detected when RE, T^2 , and SPE exceed their statistical thresholds.

Step 5: Tune the hyperparameters using a random search method (e.g., learning rate, batch size, number of units, dropout rate) for bidirectional LSTM /GRU models.

Step 6: Select the best hyperparameters based on performance metrics.

Step 7: Perform K -fold cross validation

Set K -folds $K = 10$

Split the dataset into K subsets.

Compute the average performance across all K runs.

Step 8: Train the final model using the entire dataset with the best hyperparameters.

Step 9: Test the model.

Step 10: Performance assessment of the model using Accuracy, Precision, Recall, and F1 score.

Step 11: Apply SHAP for a model explanation and compare it with LIME.

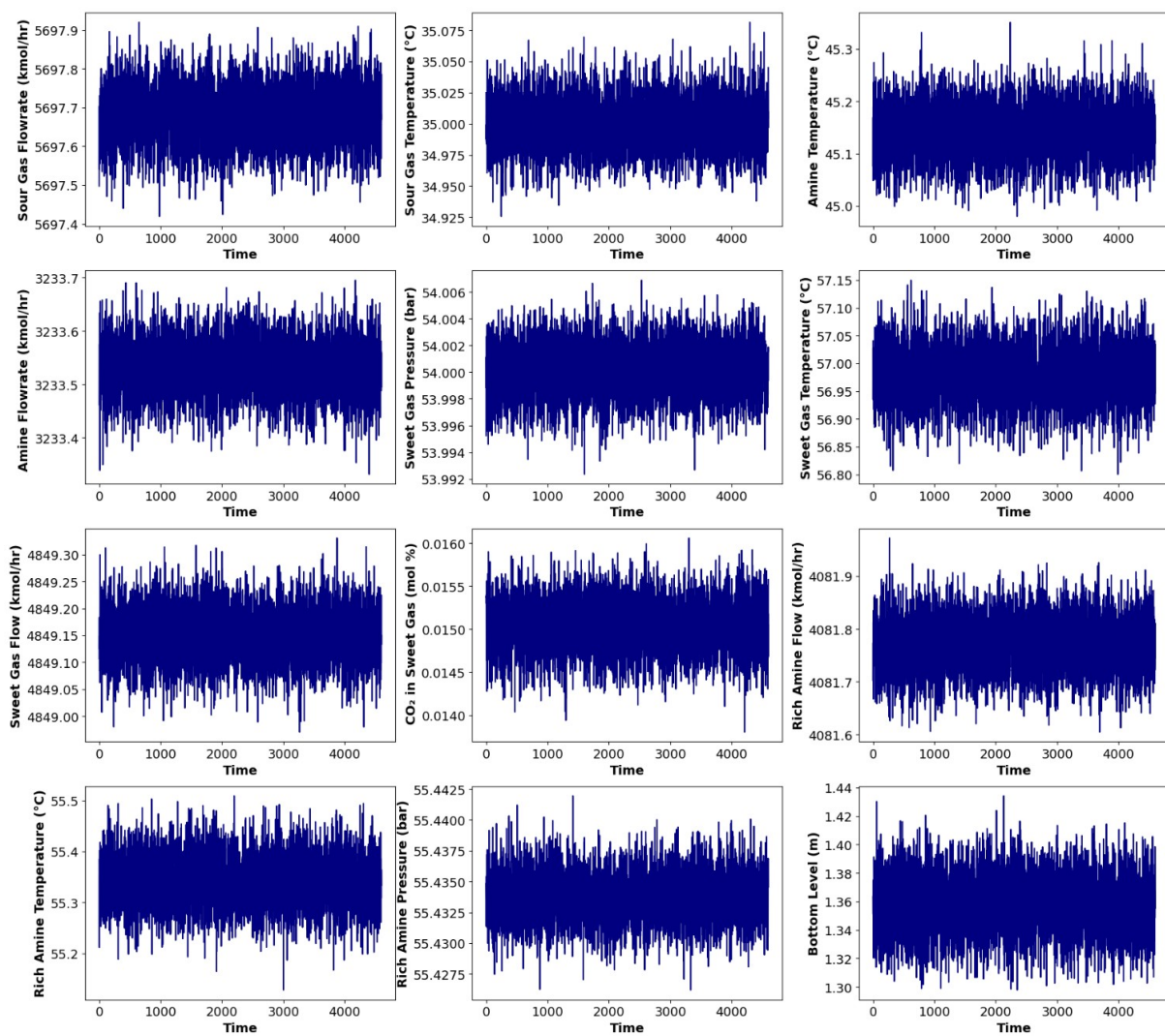


Fig. S1 Normal operation

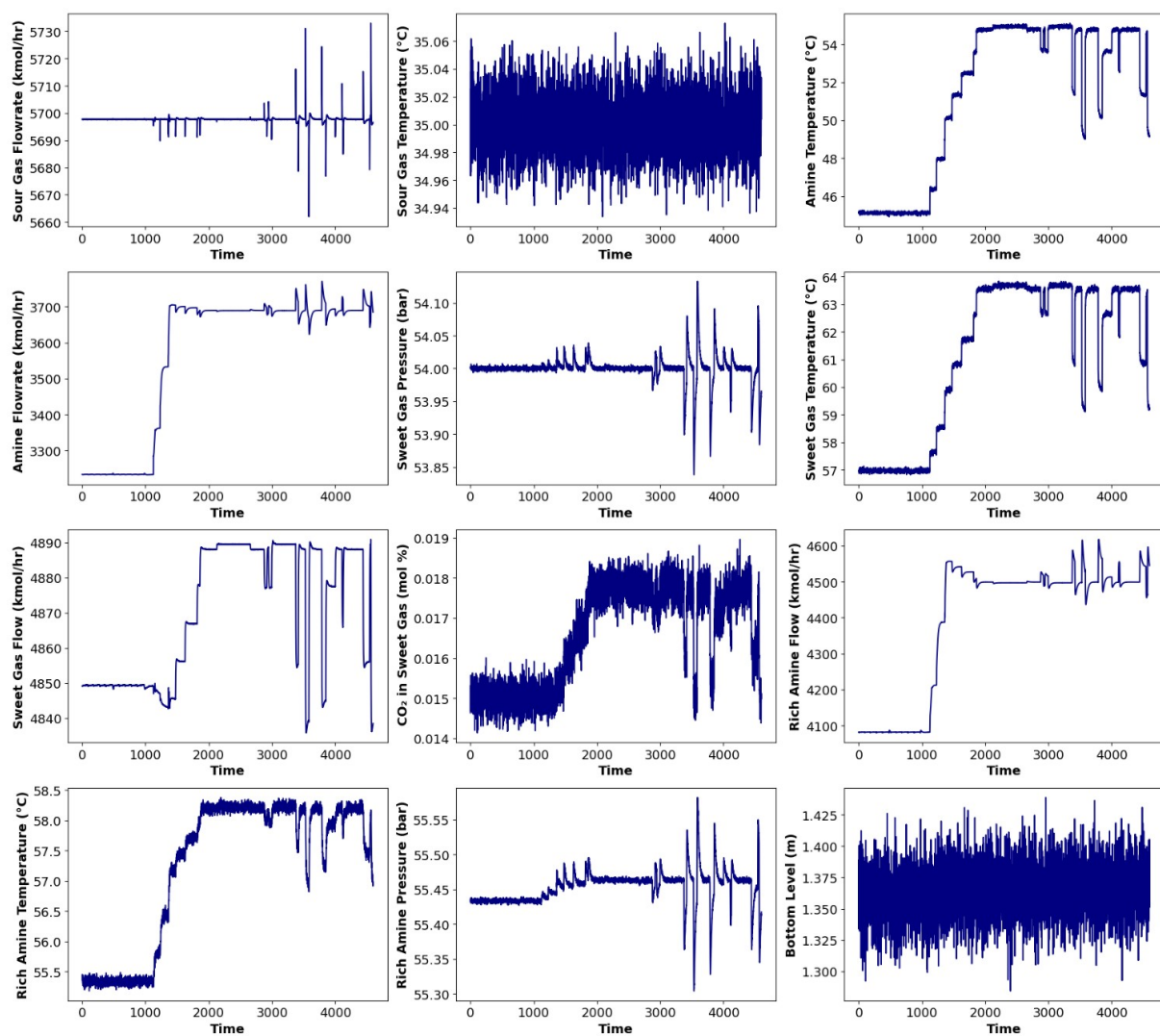


Fig. S2 Fault 1 cooler fouling

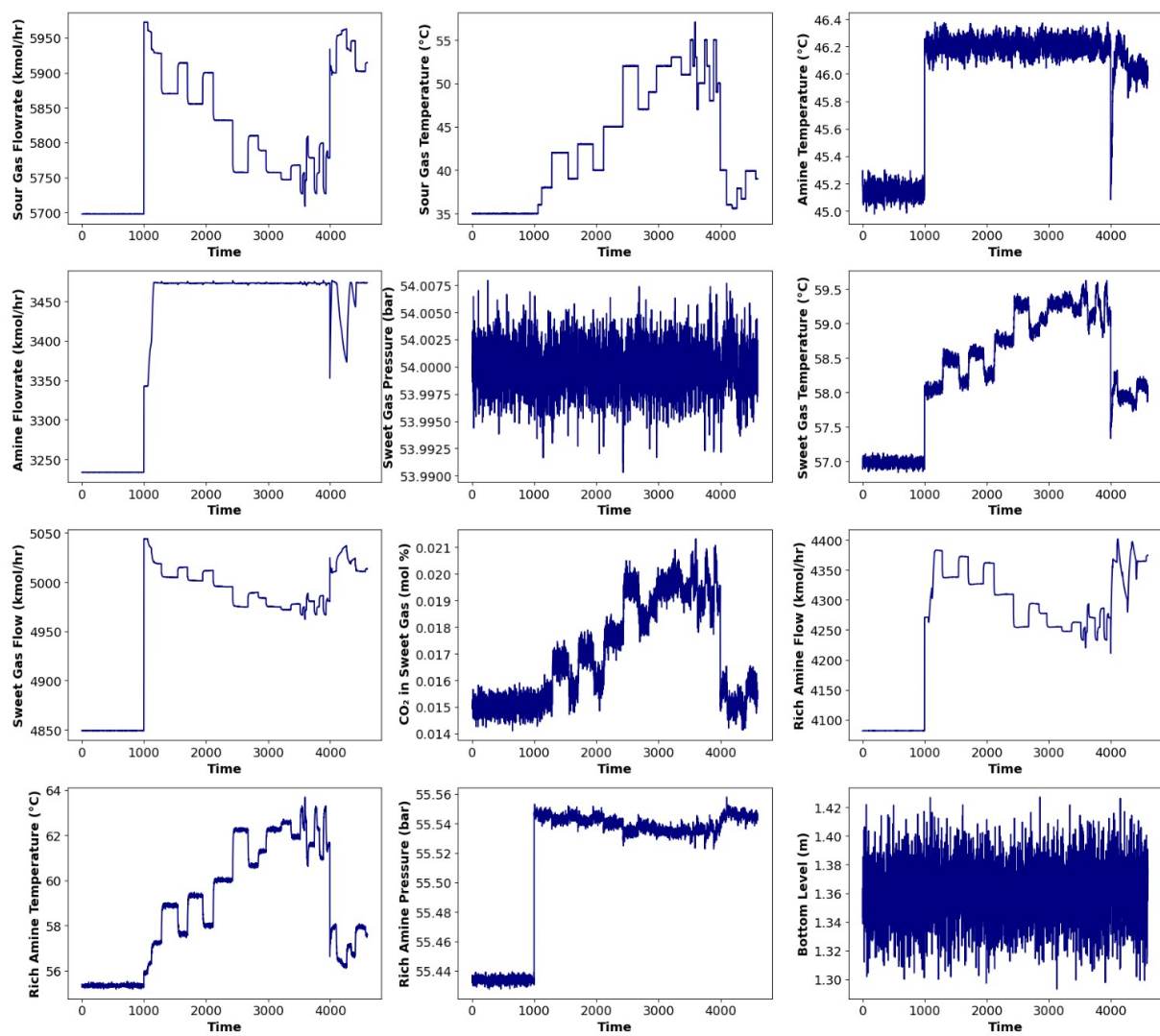


Fig. S3 Fault 2 high sour gas temperature

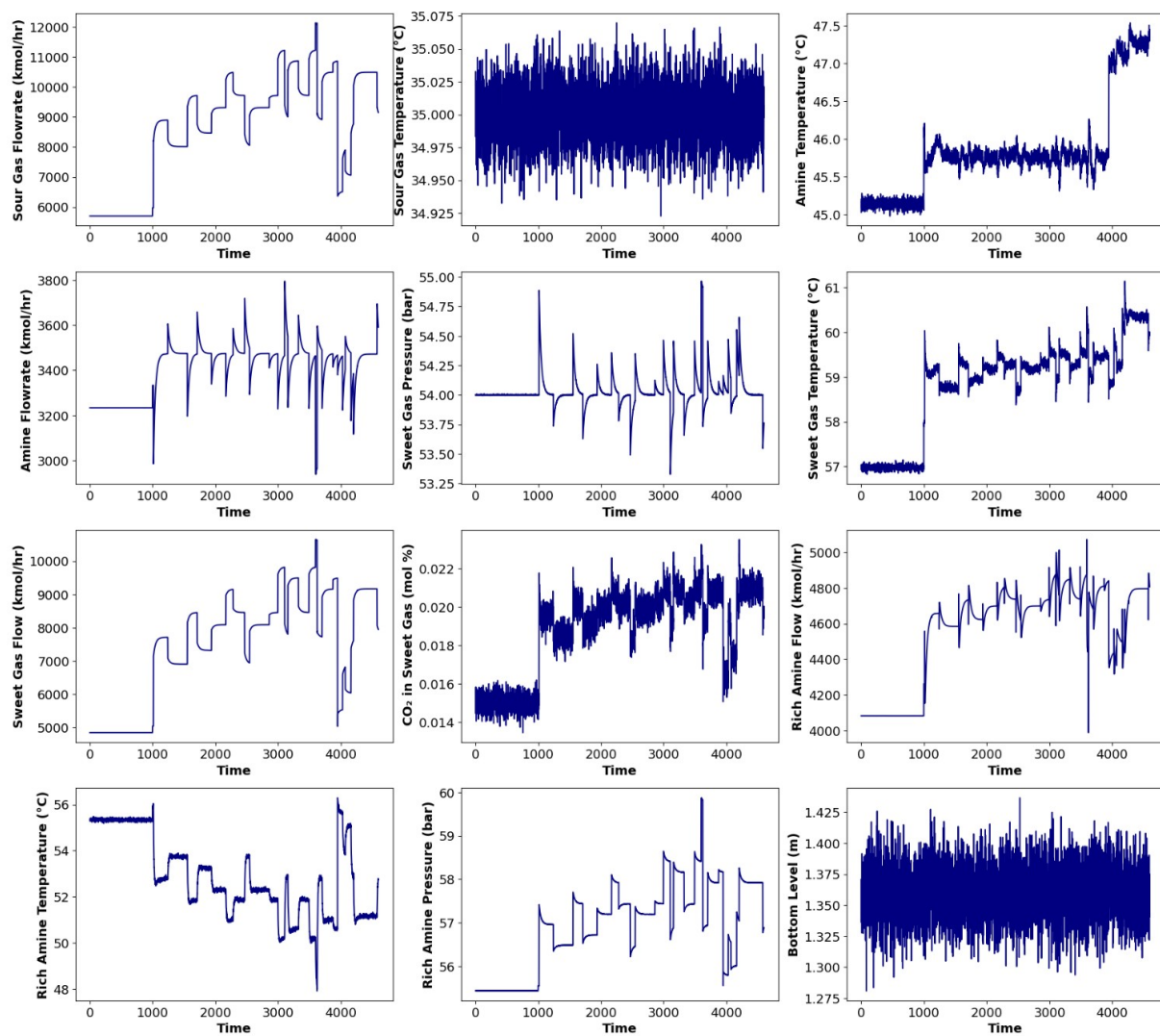


Fig. S4 Fault 3 high sour gas flow

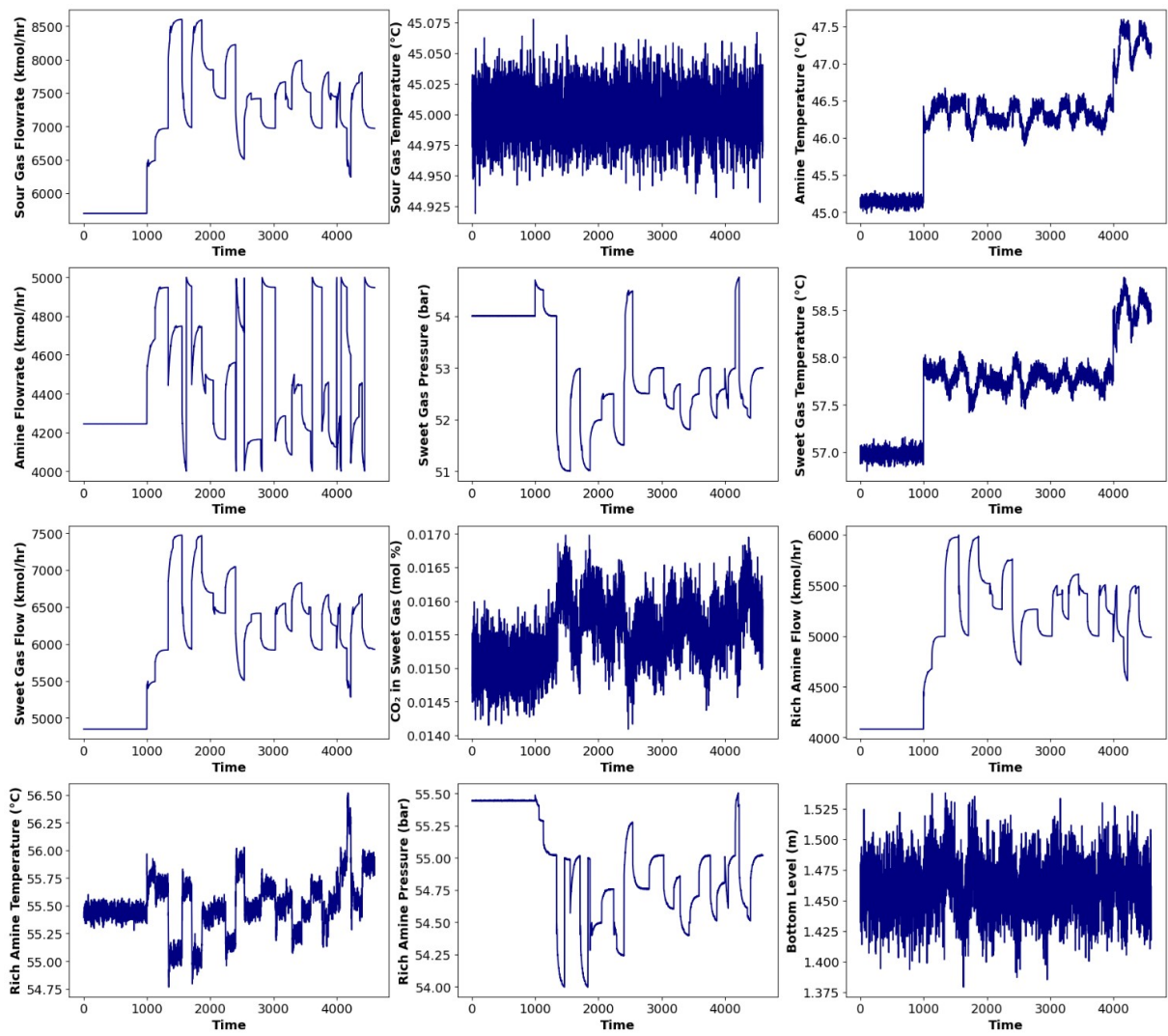


Fig. S5 Fault 4 increase in differential pressure

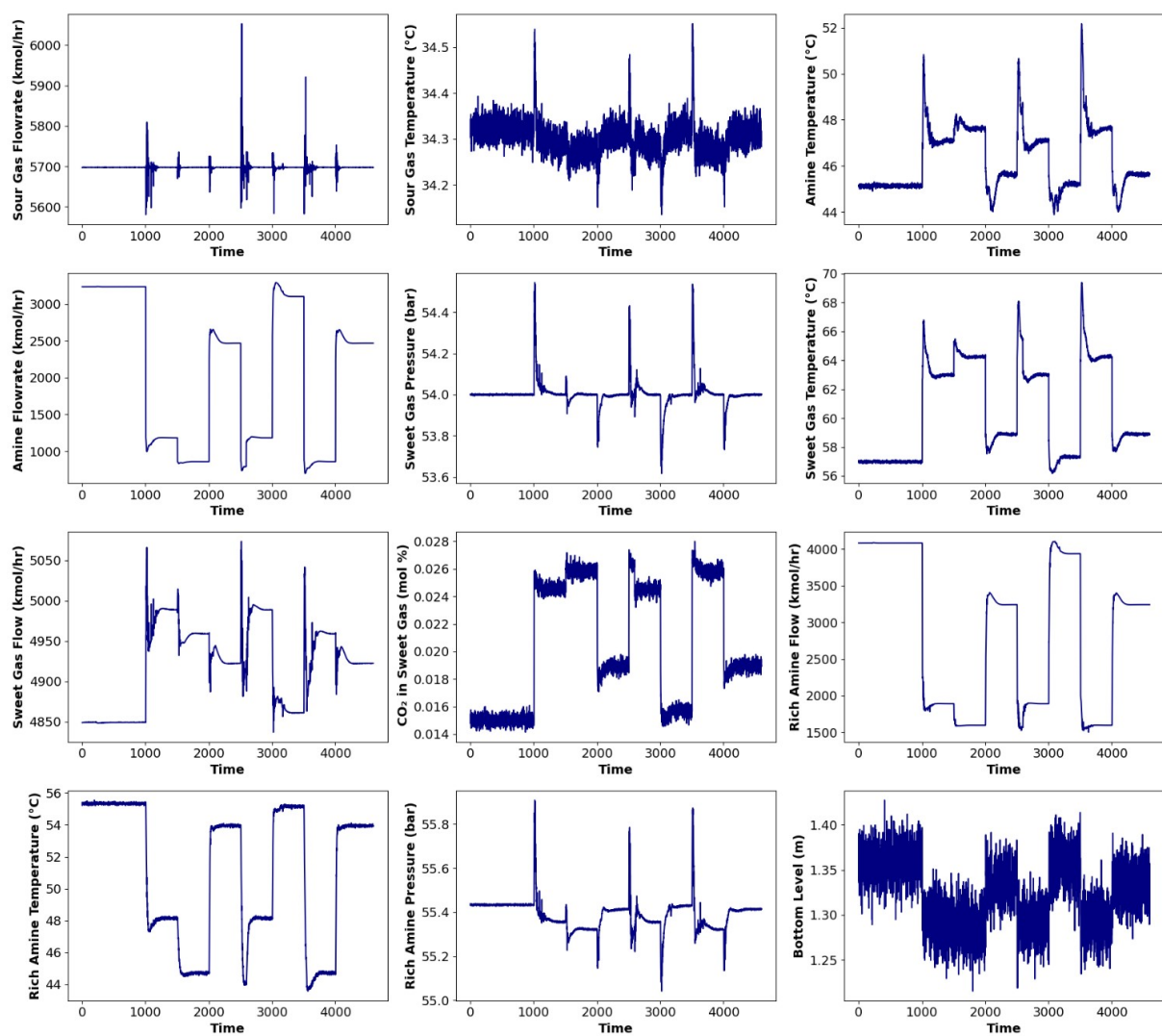


Fig. S6 Fault 5 loss of amine flow

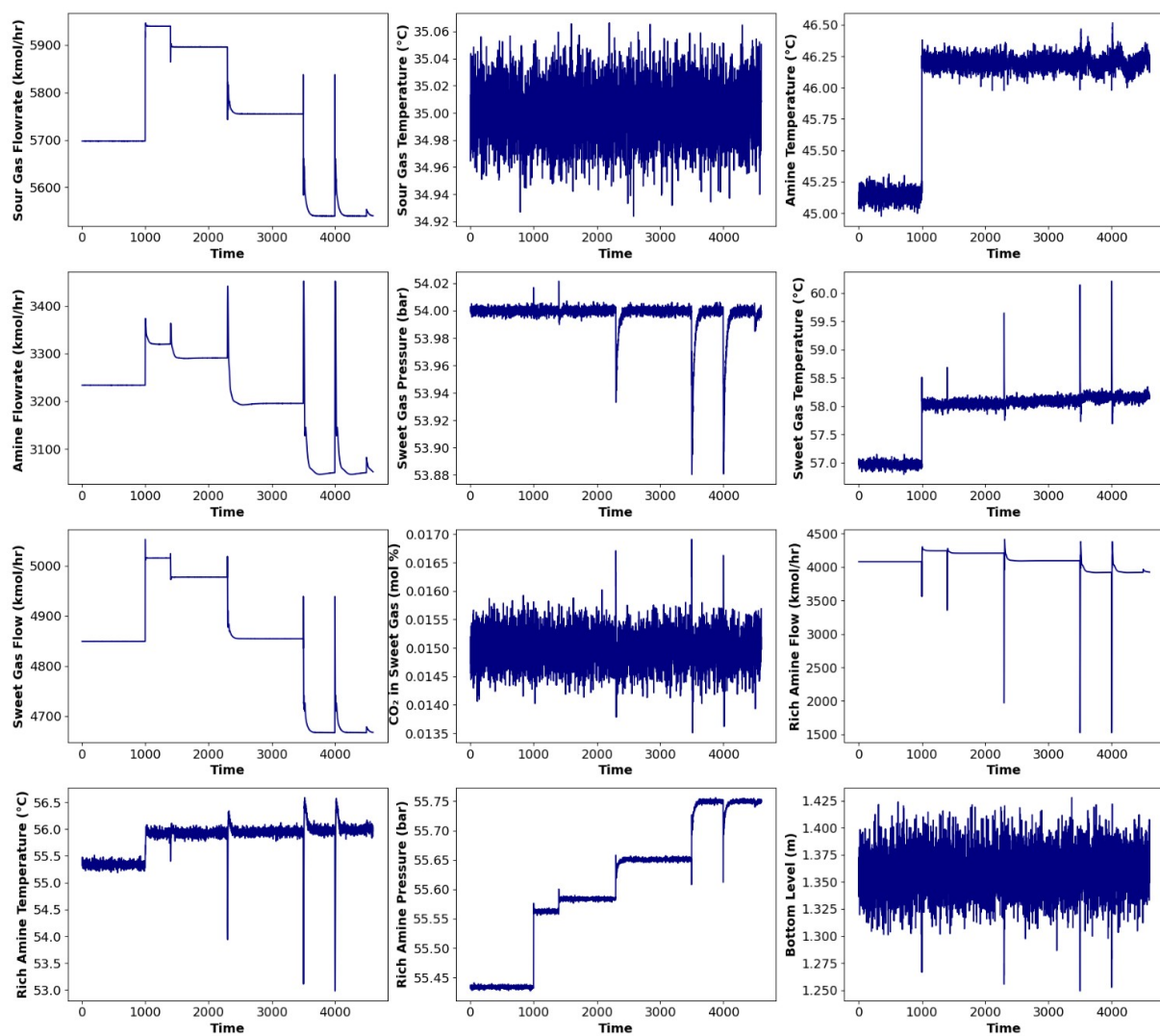


Fig. S7 Fault 6 damaged tray