# FACTORISATION OF THE FACTORIAL AN EXAMPLE OF INVERTING THE FLOW OF COMPUTATION ${ }^{1}$ 

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#### Abstract

As an example of the transformational programming method, a previously unknown algorithm for calculating factorials is derived. The derivation is done by the unfold-fold strategy with transformation rules for changing the recursion structure of functions. These transformation rules (inverting the flow of computation and splitting recursion) are presented and explained. The derivation proceeds from a system of linear recursive functions, via tail-recursive functions, to an efficient imperative program. The resulting program is, in our opinion, only intelligible by way of its derivation. It is also shown how a similar derivation leads to a version of the algorithm that may be executed on 2 processors.


Keywords: transformational programming, inversion of computation, factorial function.

## 1 Introduction

In the last decade, transformational programming has proved to be an appropriate methodology for developing programs (see, e.g., Feather, 1987; Partsch, 1990). The essence of this methodology is the derivation of (efficient) programs from formal specifications by applying semantics preserving transformations, i.e. applying a transformation rule results in a semantically equivalent program.

In a previous paper (BOITEN, 1989), we presented some transformation rules for inverting the flow of computation. Inverting the flow of computation is a transformation technique that can be applied to recursive functions, aiming at improvement of efficiency. The functions resulting from this transformation use (possibly; a.o.) the same arguments in the recursive evaluation as the original functions, but in an inverted order.

Later, we discovered a particular algebraic property of a (contrived) example function in (BOITEN, 1989). This led, via a sequence of transfor-

[^0]mations (including inverting the flow of computation) to a, to our knowledge, new algorithm for computing factorials. It also appeared possible to derive a version of the algorithm for execution on 2 processors.

This paper is organised as follows. In the next two sections our framework is introduced: the methodology, the language, and some notations specific to this paper in Section 2, and a short description of the methodology in Section 3.

In Section 4, some transformation rules (inverting the flow of computation and splitting linear recursion) that are needed later are given.

The definition of fact using the new function facthalf is presented in Subsection 4.2. It is shown in Subsection 5.1 how a particular property can be used to optimise the new algorithm for the factorial function. Subsection 5.2 shows how the algorithm in Subsection 5.1 can be optimised by inverting the flow of computation. The efficiency of the resulting algorithm may be clearer to a computer scientist than it is to a mathematician, because multiplications and divisions by 2 are not considered 'special' in mathematics. The resulting algorithm is, in our opinion, only intelligible by way of its derivation.

A derivation of a variant of the algorithm in Subsection 5.2 that might be implemented to run on 2 processors is presented in Section 6.

A more extensive report on our manipulations of the function facthalf can be found in (Boiten, 1990).

## 2 Language and Notation

In this Section we introduce some notation and present the language used in this paper.

A functional language is used that is similar to CIP-L (BAUER et al, 1985). Most of the constructs used here are self-explanatory. As in CIP-L, the semantics is strict and call-by-value. Because most functions in this paper are functions on natural numbers, the type nat of arguments and results is frequently omitted.

Many functions considered here are of the form:

$$
\begin{align*}
f(x: Q(x))= & \text { if } T(x)  \tag{2.1}\\
& \text { then } H(x) \\
& \text { else } x \oplus f(K(x)) \text { ni }
\end{align*}
$$

The predicate $Q(x)$ restricts the domain of $f$ to those elements that satisfy Q. $T(x), H(x)$, and $K(x)$ are expressions in which the variable $x$ may occur free, and in which the function $f$ does not occur. $\oplus$ and $\otimes$ (used later) denote binary operators.

The notation $f^{n}(x), n \geq 0$, denotes the $n$-fold application of $f$ to $x$, i.e.:

$$
\begin{aligned}
& f^{0}(x)=x \\
& f^{n}(x)=f\left(f^{n-1}(x)\right) \text { for } n \geq 1 .
\end{aligned}
$$

The function $g^{-1}$ denotes the inverse of $g$, provided that it exists. $\left(g^{-1}\right)^{k}(x)$ is abbreviated to $g^{-k}(x)$.

## 3 Methodology

A derivation in the transformational programming methodology is presented. The essence of this methodology is the derivation of (efficient) programs from formal specifications by applying semantics preserving transformations, i.e. applying a transformation rule results in a semantically equivalent program.

The strategy we use is mainly the unfold-fold strategy (Burstall and Darlington, 1977). Unfolding is the substitution of a function call by the body of the function, with substitution of the formal parameters by the actual parameters. Folding is the inverse of unfolding, i.e., an instance of a function body is replaced by a function call with suitable parameters.

Most phases of the derivation start with the introduction of a new function, defined in terms of existing ones. Some motivation is usually given for the introduction of the new function, we refer to well-known strategies like finite differencing (Paige and Koenig, 1982) and accumulation (Bird, 1984). Function calls are unfolded, often simplifications and rearrangements are done, until by folding an independent version of the new function can be obtained.

In this paper, some special transformation rules will be used as well (cf. Section 4). These are rules that require more complicated inductive proofs than can be provided by unfolding and folding only.

## 4 Transformation Pinles

In this Section, we present three transformation rules to be used in the rest of this paper. The first two invert the flow of computation of functions of the form (2.1).

### 4.1 Inverting the Flow of Computation

We aim at transforming a function $f$ of the form

$$
\begin{align*}
f(x: Q(x)) & \text { if } T(x)  \tag{4.1}\\
& \text { then } H(x) \\
& \text { else } x \oplus f(K(x)) \mathrm{f}
\end{align*}
$$

into an equivalent function of the form:

$$
\begin{array}{ll}
f(x: Q(x)) & =f^{\prime}(c, x)  \tag{4.2}\\
& \text { where } \\
f^{\prime}(y, z: Q(y) \wedge Q(z))= & \text { if } y=z \\
& \text { then } H(c) \\
& \text { else } K^{-1}(y) \otimes f^{\prime}\left(K^{-1}(y), z\right) \mathrm{f}
\end{array}
$$

where $K^{-1}$ is the inverse of $K$, and $c$ is some fixed value, viz. the last argument to $f$ in the original computation. Intuitively, this transformation rule transforms the calculation of a term

$$
x_{1} \oplus\left(x_{2} \oplus\left(x_{3} \oplus \ldots \oplus x_{p}\right) \ldots\right)
$$

into the calculation of a term

$$
x_{p-1} \otimes\left(x_{p-2} \otimes \ldots \otimes\left(x_{2} \otimes\left(x_{1} \otimes x_{p}\right) \ldots\right)\right.
$$

Thus, a computational sequence is inverted.
As an example of a function of the form (4.1), consider the well-known factorial function, defined by:

$$
\begin{equation*}
\operatorname{fact}(x: x \geq 0)=\text { if } x=0 \text { then } 1 \text { else } x \times f a c t(x-1) \text { fi } \tag{4.3}
\end{equation*}
$$

An important notion for inverting the flow of computation is the dependency relation between function calls. We say that argument $x$ depends on argument $y$ for function $f$, denoted by $x \leftarrow_{f} y$, if the value $f(y)$ is evaluated in order to determine the value of $f(x)$. Although this description suffices for our purposes, a formal definition is given in order to show that these dependency relations can be defined operationally, and can therefore be included in the program text.

Definition 4.I $x \leftarrow_{f} y \equiv Q(x) \wedge\left(x=y \vee\left(\neg T(x) \wedge K(x) \leftarrow_{f} y\right)\right)$ (recall that $f$ is of the form in program 4.1).

## Lemma 4.1

$$
x \leftarrow_{f} y \equiv Q(x) \wedge \exists k \geq 0:\left(y=K^{k}(x) \wedge \forall i: 0 \leq i<k: \neg T\left(K^{i}(x)\right)\right)
$$

Proof. Follows directly from definition 4.1.
Often, computationally more efficient expressions for the dependency relation $\leftarrow_{f}$ can be derived. As an example, the following holds according to definition 4.1:

$$
x \leftarrow_{\text {fact }} y \equiv x \geq 0 \wedge\left(x=y \vee\left(x \neq 0 \wedge x-1 \leftarrow_{\text {fact }} y\right)\right),
$$

where fact is as defined above.
It can even be simplified to the following non-recursive expression:

$$
x \leftarrow_{\text {fact }} y \equiv 0 \leq y \leq x .
$$

As shown in Section 4, the simplification of such expressions for function call dependencies may be an important step in inverting the flow of computation.

The computational sequence of the original factorial function, viz.

is transformed by transformation rule 4.3 into


More general conditions for this transformation rule can be found in (BOITEN, 1989). If we restrict ourselves to the most simple case, viz. where $\otimes \equiv \oplus$, we have:

## Transformation 4.1

Defined and deterministic functions $f$ of the form
(4.4) $\quad f(x: Q(x))=$ if $T(x)$ then $H(x)$ else $x \oplus f(K(x)) \mathbf{n}$
are equivalent to

$$
\begin{align*}
f(x: Q(x)) \quad & =f^{\prime}(c, x)  \tag{4.5}\\
& \text { where } \\
f^{\prime}(y, z: Q(y) \wedge Q(z))= & \text { if } y=z \\
& \text { then } H(c) \\
& \text { else } K^{-1}(y) \oplus f^{\prime}\left(K^{-1}(y), z\right) \mathbb{i}
\end{align*}
$$

under the following conditions:

1. $K$ is invertible, i.e. a function $K^{-1}$ exists that fullfils

$$
\forall x: \neg T(x) \Rightarrow K^{-1}(K(x))=x
$$

2. $\oplus$ is left-commutative

$$
\forall x, y, z: x \oplus(y \oplus z) \equiv y \oplus(x \oplus z)
$$

3. every function call $f(x)$ depends on $f(c)$ :

$$
T(c) \wedge \forall x: Q(x): x \leftarrow_{f} c .
$$

In particular, when

$$
T(x) \equiv x=q
$$

then we have $c=q$ in the transformed $f$.
So far, we have dealt only with functions for which a left inverse of $K$ exists. For the inversion of computation it is, however, not necessary at all that the left inverse of $K$ exists.

In the inverted version above, after determining the value of $f(y)$, $K^{-1}(y)$ is used to determine the value $z$ such that $K(z)=y$. Note that this always takes place in the context of the inverted computation of $f(x)$ for a certain $x$. Although there may be multiple values $z$ such that $K(z)=y$, only one of those values actually occurs as an argument of $f$ in the computation of $f(x)$. Paterson and Hewitt (1970) have shown that such a $z$ can always be found, albeit in an inefficient way. This is done by reconstructing all arguments $K^{i}(x)$ for $i=1 \ldots j$ such that $K^{j}(x)=y$. Such a $j$ always exists, because $y$ occurs as an argument to $f$ in the computation of $f(x)$. The argument that precedes the argument $y$ in the computation of $f(x)$ is $K^{j-1}(x)$. Formally, this way of finding in the context of the computation of $f(x)$ a $z$ such that $K(z)=y$ can be defined by:

$$
\begin{aligned}
K_{\text {Pat Hew }}^{-1}\left(x, y: \exists j \geq 1: y=K^{j}(x)\right)= & \text { if } y=K(x) \\
& \text { then } x \\
& \text { else } K_{\text {PatHew }}^{-1}(K(x), y) \mathbf{n}
\end{aligned}
$$

We still use the symbol $K^{-1}$, because it denotes the inverse relation of $K$, restricted to the set $\left\{y \mid x \leftarrow_{f} y\right\}$. This will be called a generalised left inverse function.

A transformation rule similar to 4.1 can be given which uses the generalised inverse. The most important difference with the previous transformation rule is the incorporation of the argument $x$ in the generalised left inverse $K^{-1}$. Also, the requirement that the starting value $c$ is independent of the argument $x$ has been dropped.

## Transformation 4.2

Defined and deterministic functions $f$ of the form

$$
\begin{align*}
f(x: Q(x))= & \text { if } T(x)  \tag{4.6}\\
& \text { then } H(x) \\
& \text { else } x \oplus f(K(x)) \mathbf{f i}
\end{align*}
$$

are equivalent to

$$
\begin{align*}
& f(x: Q(x))= f^{\prime}(c)  \tag{4.7}\\
& \text { where } \\
&= \text { that } k: T(k) \wedge x \leftarrow_{f} k \\
& c=\operatorname{if} y=x \\
& f^{\prime}(y: Q(y)) \\
& \text { then } H(c) \\
& \quad \text { else } K^{-1}(x, y) \oplus f^{\prime}\left(K^{-1}(x, y)\right) \mathbf{f}
\end{align*}
$$

under the following conditions:

1. $K^{-1}$ is the generalised inverse of $K$, i.e.

$$
\forall x, y:\left(x \leftarrow_{f} y \wedge \neg T(y)\right) \Rightarrow K^{-1}(x, K(y))=y ;
$$

2. $\oplus$ is left-commutative

$$
\forall x, y, z: x \oplus(y \oplus z) \equiv y \oplus(x \oplus z)
$$

A useful lemma for finding more efficient generalised left inverses is the following:

## Lemma 4.2

$K_{P a t H e w}^{-1}\left(x, y: \exists j \geq 1: y=K^{j}(x)\right) \equiv$ that $z: \neg T(z) \wedge K(z)=y \wedge x \leftarrow_{f} z$

### 4.2 Splitting Linear Recursion

In (BOITEN, 1989), the following alternative definition of the factorial function was presented:
(4.8) $\operatorname{fact}(x)=$ if $x=0$ then 1

$$
\begin{aligned}
& \text { where } \begin{aligned}
\text { wacthal } f(x)= & \text { if } x \leq 1 \\
& \text { then } 1 \\
& \text { else } x \times \text { facthal } f(x-2) \times \operatorname{facthal} f(x-1) \mathrm{f}
\end{aligned}
\end{aligned}
$$

It is clear that the above function calculates the factorial of a number by calculating the products of the odd and even factors separately. Intuitively, its correctness is obvious. Formally, it is guaranteed by the correctness of the following transformation rule, which is proved in (BOITEN, 1990):
Transformation 4.3

Defined functions $f$ of the form

$$
\begin{align*}
f(x)= & \operatorname{if} T(x)  \tag{4.9}\\
& \text { then } H(x) \\
& \text { else } Q(x) \oplus f(K(x))
\end{align*}
$$

are equivalent to

$$
\begin{align*}
f(x)= & \text { if } T(x)  \tag{4.10}\\
& \text { then } \oplus_{j=0}^{-1} Q\left(K^{j}(x)\right) \oplus H(x) \\
& \text { elsf } T(K(x)) \\
& \text { then } \oplus_{j=0}^{0} Q\left(K^{j}(x)\right) \oplus H(K(x)) \\
& \cdots \\
& \text { elsi } T\left(K^{n-1}(x)\right) \\
& \text { then } \bigoplus_{j=0}^{n-2} Q\left(K^{j}(x)\right) \oplus H\left(K^{n-1}(x)\right) \\
& \text { else } \oplus_{i=0}^{n-1} f n\left(K^{i}(x)\right) \\
& \text { ㄴ }
\end{align*}
$$

Where
$f n(x)=$ if $T(x)$ then $H(x)$
elsf $\exists_{i=1}^{n-1} T\left(K^{i}(x)\right)$
then $Q(x)$
else $Q(x) \oplus f n\left(K^{n}(x)\right)$
fi
for any $n \geq 1$, provided that the operator $\oplus$ is associative and commutative, with unit element $1_{\oplus}$. The expressions $\bigoplus_{i=p}^{q} g(i)$ are defined by:

$$
\bigoplus_{i=p}^{q} g(i)= \begin{cases}1_{\oplus} & \text { if } p>q \\ g(p) \oplus\left(\bigoplus_{i=p+1}^{q} g(i)\right) & \text { otherwise }\end{cases}
$$

Note that the only expression of the form $\bigoplus_{i=p}^{q} g(i)$ that does not contain a term syntactically different from $1_{\oplus}$ occurs only in the context $\oplus_{i=p}^{q} g(i) \oplus$ $H(x)$. That means that, for fixed $n$, all expressions of the form $\bigoplus_{i=p}^{q} g(i)$ in the transformation rule may be eliminated or simplified to expressions not containing $1_{\oplus}$. So, the value $1_{\oplus}$ may be fictitious, i.e. if no unit of $\oplus$ exists, a new element $1_{\oplus}$ may be adjoined to the type of $\oplus$ 's operands. The only property that is required of the new value $l_{\ominus}$ is that for all $t$ $x: x \oplus 1_{\ominus}=x$.

Intuitively, this transformation rule splits the calculation of a term

$$
x_{1} \oplus x_{2} \oplus x_{3} \oplus \ldots \oplus x_{p}
$$

into $n$ calculations of terms

$$
\begin{gathered}
x_{1} \oplus x_{n+1} \oplus x_{2 n+1} \oplus \ldots, \\
x_{2} \oplus x_{n+2} \oplus x_{2 n+2} \oplus \ldots, \\
\ldots \\
x_{n} \oplus x_{2 n} \oplus x_{3 n} \oplus \ldots
\end{gathered}
$$

Thus, a computational sequence is transformed into a computational tree with $n$ branches.

The computational sequence of the original factorial function, viz.

is transformed by transformation rule 4.3 into

(for $x \geq 3$ ). Thus, one computation is split up into two independent computations that may be executed in parallel. It is clear that transformation rule 4.3 may be used for the evaluation of certain kinds of linear recursive functions on architectures with a fixed number ( $\geq 2$ ) of processors.

## 5 Transformational Development

### 5.1 A Property of facthalf

By induction, it can easily be proved that the following property holds for the function facthalf in program (4.8).

$$
\begin{equation*}
\operatorname{even}(x) \Rightarrow \text { facthal } f(x)=2^{x / 2} \times f a c t(x / 2) \tag{1}
\end{equation*}
$$

This property is also mentioned in (PURDON and Brown, 1985, exercise 4 on page 98 ). In the following, / denotes integer division.

```
        facthal \(f(x) \times\) facthal \(f(x-1)\)
        if odd \((x)\)
        then facthal \(f(x) \times 2^{(x-1) / 2} \times f \operatorname{act}((x-1) / 2)\)
        else \(f a c t(x / 2) \times 2^{x / 2} \times\) facthal \(f(x-1)\)
        R
    \(=\{\) use mod, comm. \(\times\} \quad\) facthal \(f(x-1+x \bmod 2) \times 2^{x / 2} \times f \operatorname{fact}(x / 2)\)
```

Finally, it is clear that all arguments to facthalf are odd. When we add this to the assertion in facthalf, and simplify facthalf accordingly, we have altogether:

```
fact(x)
    = if }x=0\mathrm{ then 1
        else facthalf(x-1+x\operatorname{mod}2)\times\mp@subsup{2}{}{x/2}\timesfact(x/2)
        fi
    where
    facthalf(x:x\geq1^\operatorname{odd(x))}
    = if x=1
    then 1
    else }x\times\mathrm{ facthal f(x-2)n
```

This is our second, in our view surprising version of fact, which uses mainly subtraction and division by 2 instead of subtraction by 1 in its recursion.

### 5.2 Possibilities for improving fact/facthalf

As an example, consider the evaluation of $f a c t(31)$. By repeatedly unfolding fact, we get:

$$
\begin{aligned}
f a c t(31)= & \text { facthal } f(31) \times \text { facthal } f(15) \times f \text { acthal } f(7) \times \\
& \text { facthal } f(3) \times \text { facthal } f(1) \times 2^{26}
\end{aligned}
$$

Obviously,

$$
\text { facthal } f(31)=31 \times 29 \times \ldots \times 17 \times \text { facthal } f(15),
$$

i.e., there is some redundancy in the computation. We are, however, not able as yet to eliminate that redundancy. This is because facthalf(31) is computed 'first', and only later is the intermediate result facthalf(15) again useful. Therefore, we aim at inverting the flow of computation of fact. The result of that is that $f a c t(15)$ is computed first in the computation of $f a c t(31)$, and it is multiplied only afterwards with the value of facthalf(31). Thus, facthalf(15) is used before facthalf(31), and can be used as a starting value for computing facthalf(31). If we want to do so, we have to find a version of facthalf that computes as facthalf(31) as $(\ldots(($ facthal $f(15) \times 17) \times 19) \times \ldots) \times 31$. This can be achieved by also inverting the flow of computation of facthalf.

### 5.3 Transforming facthalf

Transformation rule 4.1 can be applied to facthal $f$, resulting in:
(5.3) $\operatorname{facthalf}(x: x \geq 1 \wedge \operatorname{odd}(x))$
$=f h(1, x)$
where
$f h(y, x: x \geq y \geq 1 \wedge \operatorname{odd}(x) \wedge \operatorname{odd}(y))$
$=$ if $y=x$
then 1
else $(y+2) \times f h(y+2, x)$ in
The correctness of this version is guaranteed by the invertibility of $K(x)=$ $x-2$ and the commutativity of multiplication.

We now prove a lemma that will be useful later in the derivation.

## Lemma 5.1

For all $p, q, x$ such that $1 \leq p \leq q \leq x \wedge \operatorname{odd}(p) \wedge \operatorname{odd}(q) \wedge \operatorname{odd}(x)$, $f h(p, x)=f h(p, q) \times f h(q, x)$.
Proof: Intuitively it is clear that the lemma holds, because $f h(p, q)$ is simply the product of all odd numbers from $p \neq 2$ up to $q$. Formally, this can be proved by induction on $q-x$.
Basis. If $q-x=0$, then $f h(p, x)=f h(p, x) \times 1=f h(p, q) \times f h(q, x)$.
Induction. Suppose the lemma holds for $x-2 k \leq q \leq x$. Then

$$
\begin{aligned}
& f h(p, x-2 k-2) \times f h(x-2 k-2, x)=\{\text { unfold } f h\} \\
& f h(p, x-2 k-2) \times(x-2 k) \times f h(x-2 k, x)=\{\text { fold } f h, \text { commutativity } \times\} \\
& f h(p, x-2 k) \times f h(x-2 k, x)=\{\text { induction }\} \\
& f h(p, x) .
\end{aligned}
$$

Because multiplication is associative, the accumulation strategy (BIRD, 1984) can be applied by definition of

$$
\begin{equation*}
f h f(x, y, r e s)=r e s \times f h(x, y) \tag{2}
\end{equation*}
$$

resulting in:
(5.4) facthalf(x:x $\geq 1 \wedge \operatorname{odd}(x))$

$$
=\quad f h f(1, x, 1)
$$

where

$$
f h f(y, x, \text { res }: x \geq y \geq 1 \wedge \operatorname{odd}(x) \wedge \operatorname{odd}(y))
$$

$$
=\quad \text { if } y=x
$$

then res
else $f h f(y+2, x$, res $\times(y+2))$
fi
The function $f h f$ can be transformed into iterative form, because it is tail recursive. Then we have:

```
\(5.5 \quad f h f(y, x\), res \(: x \geq y \geq 1 \wedge \operatorname{odd}(x) \wedge \operatorname{odd}(y))\)
    \(=\) begin \(\operatorname{var}(v y, v x, v r e s):=(y, x, r e s)\);
            while \(v y \neq v x\)
            do \((v y, v x\), vres \():=(v y+2, v x\), vres \(\times(v y+2))\)
            od;
            vres
    end
```

This can be simplified by eliminating all assignments to $v x$ and replacing all other occurrences of $v x$ by $x$, yielding:

```
5.6 fhf(y,x,res:x\geqy\geq1^odd(x)^odd(y))
    = begin var(vy,vres):= (y,res);
        while vy\not=vx
        do (vy,vres):=(vy+2,vres }\times(vy+2)
        od;
        vres
```

    end
    
### 5.4 Transforming fact

As mentioned before, in order to profit from the new version of facthalf, we need to invert the flow of computation of fact as well. Furthermore, some optimisations (viz. accumulation and finite differencing) are possible afterwards.

First the complicated expression $x-1+(x \bmod 2)$ is abstracted. Note that it denotes the greatest odd number less than or equal to $x$. This definition of toodd is used throughout this paper.

$$
\begin{equation*}
\operatorname{toodd}(x: x>0)=x-1+(x \bmod 2) \tag{5.7}
\end{equation*}
$$

The function fact can now be improved by inverting the flow of computation. This will be done along the lines of Section 4.

If $K(x)=x / 2$ were invertible, transformation rule 4.1 would be applicable. This is not the case, and thus we should find a generalised left inverse of $K$ in order to apply transformation rule 4.2 . Since $K^{j}(x)=x / 2^{j}$, we can define $K^{-1}$, using lemma 4.2, by:

$$
\begin{equation*}
K^{-1}\left(x, y: \exists k>0: y=x / 2^{k}\right)=\text { that } z: z / 2=y \wedge \exists k: z=x / 2^{k} \tag{5.8}
\end{equation*}
$$

Later on, an efficient definition of $K^{-1}$ can be given. The definition of $K^{-1}$ will not be repeated in the derivations. Using transformation rule 4.2 , we now invert the flow of computation of fact, resulting in:

$$
\begin{align*}
& f a c t(x)=f a c t^{\prime}(0)  \tag{5.9}\\
& \text { where } \\
& f a c t^{\prime}(y) \\
& =\quad \text { if } y=x \\
& \quad \text { then } 1 \\
& \quad \text { else } 2^{y} \times f a c t h a l f(\text { toodd }(n y)) \times \text { fact }^{\prime}(n y) \\
& \quad \text { where } n y=K^{-1}(x, y)
\end{align*}
$$

$$
\mathrm{fi}
$$

By using the definition of facthalf above, the else-branch transforms into:

$$
2^{y} \times f h f(1, \operatorname{toodd}(n y), 1) \times f a c t^{\prime}(n y) .
$$

The next goal is now improvement of fact by finite differencing. We aim at carrying along the value of $f h f$ last computed. Furthermore, because the last call of $f h f$ has toodd $(n y)$ as an argument, the value of toodd $(n y)$ will also be kept. First we define a new function fact ${ }^{\prime \prime}$ with appropriate assertion (note that when $y=0$, no $f h f$ value has been computed yet, and thus the assertion should give no extra information):
(5.10) $f a c t^{\prime \prime}(y, z, o d d y:$

$$
=f a c t^{\prime}(y)
$$

$$
y \neq 0 \Rightarrow(\operatorname{odd} y=\operatorname{toodd}(y) \wedge z=f h f(1, o d d y, 1)))
$$

By unfolding, abstraction and simplification we get:

```
\(f a c t^{\prime \prime}(y, z, o d d y:\)
        \(y \neq 0 \Rightarrow(o d d y=\operatorname{toodd}(y) \wedge z=f h f(1, o d d y, 1)))\)
    \(=\) if \(y=x\)
        then 1
        else \(2^{y} \times f h f\left(1, \operatorname{toodd}(n y), 1 \times f a c t^{\prime}(n y)\right.\)
        where \(n y=K^{-1}(x, y)\)
        fi
```

The following simplification is possible:

```
fhf(1,toodd(ny),1)
    ={lemma 5.1, def. fhf} fhf(1,oddy,1)\timesfhf(oddy,toodd(ny),1)
    ={(2)}}\quadfhf(oddy,toodd(ny),fhf(1,oddy,1)
    ={assertion fact"'} foff(oddy,toodd(ny),z)
```

Using this, we can fold fact" (the fhf value just computed is the correct new value for $z$, according to the assertion), resulting in:

$$
\begin{align*}
& \text { fact" }(y, z, o d d y \text { : }  \tag{5.12}\\
& y \neq 0 \Rightarrow(o d d y=\operatorname{toodd}(y) \wedge z=f h f(1, o d d y, 1))) \\
& =\text { if } y=x \\
& \text { then } 1 \\
& \text { else } 2^{y} \times n z \times f a c t^{\prime \prime}(n y, n z \text {, oddny) } \\
& \text { where } \quad n y=K^{-1}(x, y) \text {,oddny }=\operatorname{toodd}(n y) \text {, } \\
& n z=f h f(o d d y, o d d n y, z)
\end{align*}
$$

For fact, we then have

$$
f a c t(x)=f a c t^{\prime \prime}(0,1,1)
$$

Due to commutativity of multiplication and addition, the accumulation strategy can also be applied to $f a c t t^{\prime \prime}$. We define

$$
f a c t^{\prime \prime \prime}(y, z, o d d y, r e s, t w o)=f a c t^{\prime \prime}(y, z, o d d y) \times r e s \times 2^{t w o}
$$

This allows the derivation of:

$$
\begin{align*}
& \text { fact }(x)  \tag{5.13}\\
& =\quad f^{\prime \prime \prime}\left(1 t^{\prime \prime}(0,1,1,1,0)\right. \\
& \text { where } \\
& \text { fact }^{\prime \prime \prime}(y, z, \text { oddy, res, two: } \\
& \quad y \neq 0 \Rightarrow(\text { oddy }=\text { toodd }(y) \wedge z=f h f(1, \text { odd } y, 1))) \\
& =\text { if } y=x \\
& \text { then res } \times 2^{\text {two }} \\
& \text { else fact'" }(n y, n z, \text { oddny, res } \times n z, \text { two }+y) \\
& \text { where } n y=K^{-1}(x, y), \text { oddny }=\text { toodd }(n y), \\
& n z=f h f(\text { oddy,oddny, } z) .
\end{align*}
$$

典
A parameter $n$ is added, such that $y=x / 2^{n}$. Because $n y=x / 2^{n-1}$, we have a more efficient expression for $K^{-1}$. The initial value should be $\left\lfloor{ }^{2} \log x\right\rfloor+1$ for $x>0$, since $x / 2^{\left\lfloor^{2} \log x\right\rfloor+1}=0$. Because ${ }^{2} \log 0$ is undefined, we single out 0 in the definition of fact, which results in:

$$
\begin{align*}
& f a c t(x)  \tag{5.14}\\
& =\text { if } x=0 \text { then } 1 \\
& \quad \text { else } \operatorname{fact}^{\prime \prime \prime}(0,1,1,1,0) \text { ก }
\end{align*}
$$

Note that $K^{-1}$ might be implemented even more efficiently: all first arguments to fact ${ }^{\prime \prime \prime}$ are of the form $x / 2^{k}$, and so their binary representations are prefixes of the binary representation of $x . K^{-1}$ transforms a prefix of length $n$ into a prefix of length $n+1$, and this could also be achieved by gradually shifting $x$ into a location.

Finite differencing by introduction of a parameter such that $y=x / 2^{n}$ yields:

$$
\begin{align*}
& f a \operatorname{fit}(x)  \tag{5.15}\\
& =\text { if } x=0 \text { then } 1
\end{align*}
$$

```
    else fact"'\prime\prime}(0,1,1,1,0,\mp@subsup{\lfloor}{}{2}\operatorname{log}x\rfloor+1)\mathbf{fl
    where
fact ''I\prime\prime}(y,z,oddy,res,two,n
    oddy = toodd (y) \wedgez=fhf(1,oddy,1) ^y=x/2n}
= if }y=
    then res }\times\mp@subsup{2}{}{\mathrm{ two}
    else fact"'\prime\prime}(ny,nz,oddny,res\timesnz,y+two,n-1
        where }ny=x/\mp@subsup{2}{}{n-1},oddny=\operatorname{toodd}(ny)
            nz=fhf(oddy,oddny,z)
    n
```


### 5.5 The Imperative Level

Because fact ${ }^{\prime \prime \prime \prime}$ is tail recursive, we can transform (5.15) (with unfolding of all value abstractions and the imperative counterpart of $f a c t^{\prime \prime \prime \prime}$ ) into:

```
fact(x)
= if x=0 then 1 else
    begin
            var (vy,vz,voddy,vres,vtwo,vn):= (0,1,1,1,0, \lfloor\mp@subsup{}{}{2}\operatorname{log}x\rfloor+1);
            while vy\not=x
            do
                (vy,vz,voddy,vres,vtwo,vn) :=
                (x/2 vn-1},fhf(voddy,toodd(x/\mp@subsup{2}{}{vn-1}),vz),toodd(x/\mp@subsup{2}{}{vn-1}
                ,vres}\timesfhf(voddy,toodd(x/\mp@subsup{2}{}{vn-1}),vz),vtwo +vy,vn-1
            od;
            vres }\times\mp@subsup{2}{}{vtwo
        end fi
```

The inner assignment statement can be sequentialised as follows:

```
vtwo:= vtwo + vy;
vn:=vn-1;
vy:=x/2v;
vz:= fhf(voddy,toodd(vy),vz);
voddy:= toodd(vy);
vres:= vres }\timesv
```

Now we unfold $f h f$ in the assignment to $v z$, yielding:

```
vz:= begin
    var (va,vb):= (voddy,vz);
```

```
    while \(v a \neq\) toodd \((v y)\)
    do \((v a, v b):=(v a+2, v b \times(v a+2))\) ad
    vb
end;
```

The following optimisations are now possible:

- because va is initialised with voddy, and voddy is not used in the inner loop, and va equals toodd(vy) upon termination, voddy can replace $v a$, thereby making the assignment to voddy superfluous;
- $v b$ is initialised with $v z, v z$ is not used in the inner loop, and after the inner loop $v z$ is assigned $v b$; thus, $v z$ can replace $v b$. This can also be derived via a sequence of small transformation steps.
- The assignments in the inner loop can be sequentialised in such a way that the expression $v a+2$ (now: voddy +2 ) is computed only once.

This yields our final program, in which independent collateral assignments are not sequentialised:
(5.19) fact $(x)$

```
= iff x=0 then 1 else
    begin
        var (vy,vz,voddy,vres,vtwo,vn):= (0,1,1,1,0, \lfloor\mp@subsup{}{}{2}\operatorname{log}x\rfloor+1);
        while vy\not=x
        do vtwo:=vtwo +vy;
                        vn:=vn-1;
                vy:=x/2vn;
                while voddy }\not=\mathrm{ toodd(vy)
                        do voddy:= voddy+2;
                        vz:=vz\timesvoddy
                od;
                vтes:= vres }\timesv
            od;
            vres }\times\mp@subsup{2}{}{vtwo
        end fi
```


## 6 Implementation on Two Processors

We will demonstrate how the above algorithm can be implemented on two processors. The first processor sends a sequence of appropriate facthalf values to the second one, which computes fact using those values.

In order to derive a version of the algorithm which is close to a parallel one, we need to introduce sequences. Often, in functional descriptions
of parallel systems so-called streams are used to describe the communication (Broy and Bauer, 1984), but in this case only finite streams, i.e., sequences are needed. Because now multiple types occur in our functions, we write nat for natural number arguments and results, bool for booleans, and seq for sequences of natural numbers.

|  | The type seq |
| :--- | :--- |
| $\rangle$ | the empty sequence |
| $H$ | prepend a natural number to a sequence |
| first | the first element of a sequence |
| rest | all but the first element |

The derivation starts from the version of fact in program (5.9) nat $x$ is assumed to be known in the context. Below, a function $f a c t p 2$ is defined which is equal to $f a c t^{\prime}$, except that it takes as an extra argument the sequence of all necessary facthalf values. This is expressed by the predicate allfh.
(6.1) factp2(seq $s$, nat $y: y \leq x \wedge \operatorname{allfh}(s, y))$ nat
$=f a c t^{\prime}(y)$
where
allfh(seq $s$, nat $y$ )bool
$=$ if $y=x$ then $s=<>$
$=$ else first $s=f a c t h a l f(t o o d d(n y)) \wedge$ all $f h(n y$,rest $s)$ where $n y=K^{-1}(x, y)$ si

In order for factp 2 to replace fact ${ }^{\prime}$, we need to derive:

- a definition of factp2 independent of fact ${ }^{\prime}$, and
- a value $z$ such that $f a c t p 2(z, 0)=f_{f} a c t^{\prime}(0)$; in particular, this means that the assertion allfh(z,0) should hold.

First we derive a definition of factp2.

$$
\begin{aligned}
\text { factp } 2(s, y)=\{\text { unfold fact }\} & \text { if } y=x \text { then } 1 \\
& \text { else } 2^{y} \times \text { facthal } f(\text { toodd }(n y)) \times f a c t^{\prime}(n y) \\
& \text { where } n y=K^{-1}(x, y) \mathrm{fi} \\
=\{\text { defnition allfh }\} & \text { if } y=x \text { then } 1 \\
& \text { else } 2^{y} \times \text { frrt } s \times \text { factp } 2(\text { rest } s, n y) \\
& \text { where } n y=K^{-1}(x, y) \text { @ }
\end{aligned}
$$

The value of $s$ for the initial call can be computed from the assertion. A value $z$ is needed, such that all $f h(z, 0)$ holds. That value of $z$ will be
denoted by factp1, which implicitly depends on $x$, but also on $y$. The dependence on $y$ is necessary to derive a recursive definition of factp1. In the derivation below, $n y$ is assumed to be $K^{-1}(x, y)$.

```
factp \(1(y)=\{\) above \(\}\)
    some \(s: \operatorname{allfh}(s, y)\)
    \(=\{\) def. allf \(h\}\)
        some \(s\) : if \(y=x\) then \(s=<>\)
                        else first \(s=f a c t h a l f(\operatorname{toodd}(n y))\)
                                \(\wedge\) allfh(rest \(s, n y)\)
                        直
    \(=\{\) distributivity \(\}\)
        if \(y=x\)
    then some \(s: s=<>\)
    else some \(s\) : first \(s=\) facthal \(f(\operatorname{toodd}(n y))\)
                                    ^allfh(rest \(s, n y)\) 直
\(=\{\) some-simplification \(\}\)
    if \(y=x\)
    then <>
    else some \(s:\) first \(s=\) facthalf(toodd \((n y))\)
                        \(\wedge\) allfh(rest \(s, n y) \mathbf{f}\)
    \(=\{\) seq. decomposition \(\}\)
    if \(y=x\)
    then \(<>\)
    else facthalf(toodd(ny))
                                    \#some \(s^{\prime}: \operatorname{allf} h\left(s^{\prime}, n y\right)\) fi
    \(=\{\) fold factp 1\(\}\)
        if \(y=x\)
        then \(<>\)
        else facthalf(toodd(ny))H factp \(1(n y) \mathbb{R}\)
```

Then we have altogether:
(6.2) fact(nat $x$ )nat
$=$ factp $2($ factp $1(0), 0)$
where
factp1(nat $y$ )seq
$=$ if $y=x$
then <>
else facthalf(toodd $(n y)) H f a c t p 1(n y)$
where $n y=K^{-1}(x, y)$ fi,
factp $2($ seq $s$, nat $y)$ nat

```
= if y=x them 1
    else 2}\mp@subsup{2}{}{y}\times\mathrm{ first }s\timesfactp2(rest s,ny
    where ny= K
facthalf(nat y)nat
= if }y=1\mathrm{ then 1
    else }y\timesfacthalf(y-2) f
```

The functions factp1 and factp 2 can be optimised similarly to fact and facthalf in the previous section:

Optimise factp1:

- Define (finite differencing)

$$
\begin{aligned}
f a c t p 1(y) & =f a c t p 1^{\prime}(y, 1), \\
\text { factp1 } 1^{\prime}(y, z: y \neq 0 \Rightarrow z=\operatorname{facthal} f(\operatorname{toodd}(y))) & =\operatorname{factp} 1(y)
\end{aligned}
$$

- Use lemmia 5.1 to derive
(6.3) factpl $^{\prime}(y, z)$

$$
=\text { if } y=x \text { then }\langle>
$$

$$
\text { else } n z \# f a c t p 1^{\prime}(n y, n z)
$$

$$
\text { where } n y=K^{-1}(x, y) \text {, }
$$

fi

$$
n z=f h f(\operatorname{toodd}(y), \operatorname{toodd}(n y), z)
$$

Optimise factp2:

- Define (accumulation)

$$
\begin{aligned}
f a c t p 2(s, y) & ={\operatorname{factp} 2^{\prime}(s, y, 0,1)}^{{\operatorname{factp} 2^{\prime}(s, y, t w o, r e s)}=2^{\text {two }} \times r e s \times \operatorname{factp} 2(s, y)}
\end{aligned}
$$

- Derive
(6.4) $\mathrm{factp}^{\prime}(s, y, t w o$, res $)$

$$
=\text { if } y=x
$$

then $2^{\text {iwo }} \times$ res
else factp $^{\prime}$ (rest $s, n y$, two $+y$,res $\times$ first $s$ ) where $n y=K^{-1}(x, y)$ ni
fi

- Implement $K^{-1}$ as in the previous section.

It is clear that the sequence $s$ in factp1 and factp 2 may also be viewed as a one-way communication channel. Cf. (Broy and Bauer, 1984) for
a discussion of this kind of consumer-producer programs. The function factp 1 may be implemented on one processor, and send the computed successive first elements of $s$ to the other processor on which factp 2 is implemented.

It is even possible to use a third processor for computing the sequence of $K^{-1}$ values. In the current version, these are computed by both factp1 and factp2.

## 7 Conclusions

We have given transformation rules that split and invert computation sequences of linear recursive functions.

For the factorial function, the application of these rules and subsequent manipulations resulted in a previously unknown algorithm. The resulting algorithm appears very complicated, and is in our opinion only intelligible by way of its derivation.

In (BoRWEIN, 1985) a factorial algorithm is presented which is based on factoring out all prime factors. Its time complexity is better than that of our algorithm. However, it needs more space, viz. for a table of all prime numbers up to the argument of fact.

Finally, it was shown that the resulting algorithm may efficiently be executed on a two processor architecture.

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