

# ON GENERALIZATION OF A THEOREM OF FENYŐ

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1. It is well-known that, in general, the value of a no distribution value exists at a point does not exist. Łojasiewicz [2], however, has given a definition and criteria for the existence of the local value of a distribution at a point. According to his definition, if  $x_0$  is a fixed point and  $\tau_{x_0}$  is the operator adjoint to the shifting operator

$$\tau_{-x_0}\varphi(x) = \varphi(x - x_0),$$

where  $\varphi(x)$  is an arbitrary testing function of the space  $D(R)$ ; and  $\tau_\gamma$  is the operator adjoint to the affinity operator

$$\frac{1}{|\gamma|} \tau_\gamma \varphi(x) = \frac{1}{|\gamma|} \varphi\left(\frac{x}{\gamma}\right), \quad \gamma \neq 0;$$

then a distribution  $T$  has a local value at  $x_0$  given by

$$\lim_{\gamma \rightarrow 0} \tau_\gamma \tau_{x_0} T = t_0, \quad (1)$$

provided the limit exists.

From the above definition it is clear that in general, the value of a distribution  $T$  at a point  $x_0$  does not necessarily exist. But, if  $T$  is a distribution defined by a continuous function  $f(x)$  and  $x_0$  is in the domain of the definition of  $f$ , then the local value of this distribution exists (in the sense of Łojasiewicz) at  $x_0$ , and it is equal to  $f(x_0)$ .

Fenyő [1], on the other hand, has discussed in detail the problem of existence of the local value of a class of distribution of  $D'(R^2)$ . In fact, his investigations to assign a local value to a distribution at a point gave rise to a number of interesting problems in the field of applications of the distribution theory.

In the present paper our aim is to study the problem of existence of the local value of a certain class of distributions in the  $n$ -dimensional space.

2. Let  $D(R^n)$  be the space of testing functions  $\varphi$  of  $n$  variables and let  $D'(R^n)$  be its dual space with respect to the sequence topology of the space  $D(R^n)$ .

Let us define a mapping

$$l(a_1, a_2, \dots, a_n) : D(R^n) \rightarrow D(R)$$

in the following way:

$$\begin{aligned} l(a_1, a_2, \dots, a_n)\varphi &= \frac{1}{|a_n|} \int_{R^n} \varphi \left( \alpha_1, \alpha_2, \dots, \frac{t - a_1\alpha_1 - \dots - a_{n-1}\alpha_{n-1}}{a_n} \right) d\alpha_1 \dots d\alpha_{n-1} \\ &= \frac{1}{|a_{n-1}|} \int_{R^n} \varphi \left( \alpha_1, \alpha_2, \dots, \frac{t - a_1\alpha_1 - \dots - a_{n-2}\alpha_{n-2} - a_n\alpha_n}{a_{n-1}}, \alpha_n \right) d\alpha_1 \dots d\alpha_{n-2} d\alpha_n \\ &\dots \dots \dots \\ &= \frac{1}{|a_1|} \int_{R^n} \varphi \left( \frac{t - a_2\alpha_2 - \dots - a_n\alpha_n}{a_1}, \alpha_2, \dots, \alpha_n \right) d\alpha_2 \dots d\alpha_n, \end{aligned} \tag{2}$$

where  $a_1, a_2, \dots, a_n$  are real numbers such that at least one  $a_k \neq 0$ ;  $k = 1, 2, \dots, n$ .

From our definition it follows that  $l(a_1, a_2, \dots, a_n)\varphi$  is a function of the class  $D(R)$  and, with respect to the sequential topology of  $D(R)$ , it is also linear and continuous from the space  $D(R^n)$  into  $D(R)$ .

Denote by  $L(a_1, a_2, \dots, a_n)$  the mapping adjoint to  $l(a_1, a_2, \dots, a_n)$  given by

$$L(a_1, a_2, \dots, a_n)(T) \cdot \varphi = T \cdot l(a_1, a_2, \dots, a_n)(\varphi), \tag{3}$$

where  $T \in D'(R)$  and  $\varphi \in D(R^n)$ .

In case  $T = f$ , where  $f$  is a locally integrable function, we have

$$L(a_1, a_2, \dots, a_n)(f)(\alpha_1, \alpha_2, \dots, \alpha_n) = f(a_1\alpha_1 + a_2\alpha_2 + \dots + a_n\alpha_n).$$

Also, it is easy to see that

$$\frac{\partial}{\partial \alpha_1} L(a_1, a_2, \dots, a_n)(T) = a_1 L(a_1, a_2, \dots, a_n) \left( \frac{dT}{dt} \right),$$

$$\frac{\partial}{\partial \alpha_2} L(a_1, a_2, \dots, a_n)(T) = a_2 L(a_1, a_2, \dots, a_n) \left( \frac{dT}{dt} \right),$$

$$\dots \dots \dots$$

$$\frac{\partial}{\partial \alpha_n} L(a_1, a_2, \dots, a_n)(T) = a_n L(a_1, a_2, \dots, a_n) \left( \frac{dT}{dt} \right).$$

3. Let  $\psi$  be an arbitrary, but fixed, testing function of the class  $D(R)$ . On the lines of Fenyő (loc. cit.), let us define a linear and continuous mapping from  $D'(R^n)$  into  $D'(R^{n-1})$  denoted by  $\odot$ , as follows:

$$\begin{aligned} (S \odot \psi) \cdot \varphi &:= S \cdot \varphi \otimes \psi & \forall \varphi \in D(R^{n-1}), \\ (\psi \odot S) \cdot \varphi &:= S \cdot \psi \otimes \varphi & \forall \varphi \in D(R^{n-1}), \end{aligned} \quad (4)$$

where  $S \in D'(R^n)$  and  $\varphi \otimes \psi$  denote the tensor products of the functions given by

$$(\varphi \otimes \psi)(z_1, z_2, \dots, z_{n-1}, z) = \varphi(z_1, z_2, \dots, z_{n-1}) \cdot \psi(z),$$

that is,  $S \odot \psi$  and  $\psi \odot S$  are distributions in  $D'(R^{n-1})$ .

We shall prove the following:

*Theorem.* If  $T \in D'(R)$  and  $\psi \in D(R)$ , then the distribution

$$L(a_1, a_2, \dots, a_n)(T) \odot \psi$$

has a local value (in the sense of Łojasiewicz) at every point  $(\dot{z}_1, \dot{z}_2, \dots, \dot{z}_{n-1})$  given by

$$(L(a_1, a_2, \dots, a_n) T \odot \psi)_{(\dot{z}_1, \dot{z}_2, \dots, \dot{z}_{n-1})} = (z_{a_n} \tau_{a_1 \dot{z}_1 + \dots + a_{n-1} \dot{z}_{n-1}} \cdot T \cdot \psi).$$

4. *Proof of the theorem.* Let us consider the function

$$\begin{aligned} F(z_1, z_2, \dots, z_n) &= z_{a_n} \tau_{a_1 z_1 + \dots + a_{n-1} z_{n-1}} \cdot T \psi = \\ &= \frac{1}{a_n} T \cdot \psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right). \end{aligned} \quad (5)$$

Now, in order to prove the theorem, it will be enough to show that  $F$  is a continuous function at every point. Let  $\dot{X} = (\dot{z}_1, \dot{z}_2, \dots, \dot{z}_{n-1})$  be a fixed point in the space  $R^{n-1}$ .

Since  $\psi \in D(R)$ , there exists a positive number  $c$  such that  $\text{supp } \psi \in (-c, c)$ .

Let  $N_\varepsilon$  be a neighbourhood of the point  $\dot{X}$ ,  $\varepsilon > 0$ , then for any point  $X = (z_1, z_2, \dots, z_{n-1}) \in N_\varepsilon$ , we have

$$\begin{aligned} \text{supp}_t \psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) &\subset \\ &\subset \{|t| \leq |a_1(\dot{z}_2 + \varepsilon) + \dots + a_{n-1}(\dot{z}_{n-1} + \varepsilon)| + |a_n c|\}. \end{aligned} \quad (6)$$

Thus, we get

$$\lim_{X \rightarrow \dot{X}} \frac{d^k}{dt^k} \psi \left( \frac{t - a_1 z_2 - \dots - a_{n-1} z_{n-1}}{a_n} \right) = \frac{d^k}{dt^k} \psi \left( \frac{t - a_1 \dot{z}_2 - \dots - a_{n-1} \dot{z}_{n-1}}{a_n} \right), \quad (7)$$

$$k = 0, 1, 2, \dots,$$

uniformly for all real  $t$ .

Hence, it follows that

$$\begin{aligned} \left| \frac{d^k}{dt^k} \psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) - \frac{d^k}{dt^k} \psi \left( \frac{t - a_1 \dot{z}_1 - \dots - a_{n-1} \dot{z}_{n-1}}{a_n} \right) \right| &\leq \\ &\leq \frac{AM_k}{a_n^2} |(z_1 - \dot{z}_1) + \dots + (z_{n-1} - \dot{z}_{n-1})|, \end{aligned}$$

where  $A$  is a positive constant depending on  $a_1, a_2, \dots, a_n$  and

$$M_k = \max_{t \in R} |\psi^{(k+1)}(t)|.$$

Now, from (6) and (7), we have

$$\psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) \rightarrow \psi \left( \frac{t - a_1 \dot{z}_1 - \dots - a_{n-1} \dot{z}_{n-1}}{a_n} \right)$$

as  $X \rightarrow \dot{X}$  in the pseudo-topology of the space  $D(R)$ .

Thus, finally, we get

$$\lim_{X \rightarrow \dot{X}} T \cdot \psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) = T \cdot \psi \left( \frac{t - a_1 \dot{z}_1 - \dots - a_{n-1} \dot{z}_{n-1}}{a_n} \right).$$

This proves that  $F(z_1, z_2, \dots, z_{n-1})$  is continuous.

Let  $\varphi$  be an arbitrary function of class  $D(R^{n-1})$  and  $N_c$  a neighbourhood of the origin such that  $\text{supp } \varphi \subset N_c$ .

Hence, we find that:

$$\begin{aligned} \int_{N_c} \varphi(z_1, z_2, \dots, z_{n-1}) \psi^{(k)} \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) dz_1 \dots dz_{n-1} &= \\ = \int_{R^n} \varphi(z) \psi^{(k)} \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) dz_1 \dots dz_{n-1}. \end{aligned}$$

Therefore, it follows that:

$$\begin{aligned} T \cdot \int_{R^n} \varphi(z_1, \dots, z_{n-1}) \psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) dz_1 \dots dz_{n-1} &= \\ = \int_{R^n} \varphi(z_1, \dots, z_{n-1}) T \cdot \psi \left( \frac{t - a_1 z_1 - \dots - a_{n-1} z_{n-1}}{a_n} \right) \cdot dz_1 \dots dz_{n-1} &= \\ = |a_n| \int_{R^n} F(z_1, \dots, z_{n-1}) \varphi(z_1, \dots, z_{n-1}) dz_1 \dots dz_{n-1}. \end{aligned} \quad (8)$$

Finally, using (8) and (4), we have:

$$\begin{aligned}
 (L(a_1, a_2, \dots, a_n) \odot \psi) \cdot \varphi &= L(a_1, \dots, a_n) T \cdot \varphi(x_1, \dots, x_{n-1}) \otimes \psi(x_n) = \\
 &= T \cdot l(a_1, \dots, a_n) \varphi(x_1, \dots, x_{n-1}) \otimes \psi(x_n) = \\
 &= T \frac{1}{|a_n|} \int_{\mathbb{R}^{n-1}} \varphi(x_1, \dots, x_{n-1}) \cdot \psi \left( \frac{t - a_1 x_1 - \dots - a_{n-1} x_{n-1}}{a_n} \right) \cdot dx_1 \dots dx_{n-1} = \\
 &= \frac{1}{|a_n|} \int_{\mathbb{R}^{n-1}} \varphi(x_1, \dots, x_{n-1}) T \psi \left( \frac{t - a_1 x_1 - \dots - a_{n-1} x_{n-1}}{a_n} \right) \cdot dx_1 \dots dx_{n-1} = \\
 &= \int_{\mathbb{R}^{n-1}} F(x_1, \dots, x_{n-1}) \varphi(x_1, \dots, x_{n-1}) dx_1 \dots dx_{n-1}.
 \end{aligned}$$

This implies that the distribution  $L(a_1, \dots, a_n)(T) \odot \psi$  is identical with the function  $F(x_1, \dots, x_{n-1})$ , which is continuous at every point.

Now, using the theorem of Łojasiewicz (loc. cit., p. 7), we find that

$$\begin{aligned}
 (L(a_1, a_2, \dots, a_n)(T) \odot \psi)(\dot{x}_1, \dots, \dot{x}_{n-1}) &= F(\dot{x}_1, \dots, \dot{x}_{n-1}) = \\
 &= x_n \tau_{a_1 \dot{x}_1 + \dots + a_{n-1} \dot{x}_{n-1}} T \cdot \psi.
 \end{aligned}$$

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### Summary

Criteria for the existence of the local value of a certain class of distributions in the  $n$ -dimensional space are investigated.

### References

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