# INVESTIGATION OF LINEAR FORCE EQUATIONS WHEN CUTTING STEEL 

By<br>Ö. Rezef<br>Department of Production Engineering. Technical University. Budapest

## 1. Introduction

Cutting force is known to depend on several conditions, mainly on cutting speed and cutting geometry. Fig. 1 shows the effect of cutting geometry on cutting force, assuming idealized conditions of orthogonal cutting, where

1. Work material ( $W$, work piece, test piece)
2. Tool ( $T$ )
3. Ambient medium $(M)$
4. Cutting speed ( $v[\mathrm{~m} / \mathrm{min}]$ )
5. Cutting force ( $F_{R}[\mathrm{kp}]$ )
6. Angle $\Phi$ determining shear plane.

A chip of width $b_{d}[\mathrm{~mm}]$ contacts the tool rake face over a length $L$ [mm], thus the tool face of $b_{d} L\left[\mathrm{~mm}^{2}\right]$ is under a cutting force $F_{R}[\mathrm{kp}]$ due to an average of non-uniform load values. The symbols of cutting force components are shown in Fig. 2, in the coordinate system of tool, machine and chip. Removing undeformed chip of thickness $h[\mathrm{~mm}]$ at speed $v[\mathrm{~m} / \mathrm{min}]$, the chip $W_{d}$ really produced will be of thickness $h_{d}$.

The following known equations express the relationship between main cutting force and undeformed chip cross section:

$$
\begin{align*}
& F^{\prime}=C_{F_{h}} h^{p} b  \tag{1}\\
& F^{\prime \prime}=C_{F} h b  \tag{2}\\
& F^{\prime \prime \prime}=A^{0} A_{0}+B^{0} \tag{3}
\end{align*}
$$

The attempt to predict cutting force on the analogy of other force calculations, from strength and area, resulted in a new concept: "specific cutting force". In accordance with the three equation types it will be

$$
\begin{equation*}
k_{s}^{\prime}=\frac{C_{F_{h}}}{h^{1-p}} \quad \text { and } \quad F^{\prime}=k_{s}^{\prime} A_{0} \tag{4}
\end{equation*}
$$

$$
\begin{array}{lll}
k_{s}^{\prime \prime}=C_{F} & \text { and } & F^{\prime \prime}=k_{s}^{\prime \prime} A_{0} \\
k_{s}^{\prime \prime \prime}=A^{0}+\frac{B^{0}}{A_{0}} & \text { and } & F^{\prime \prime \prime}=k_{s}^{\prime \prime \prime} A_{0} \tag{6}
\end{array}
$$

By introducing $k_{s}$ the three equation types $(1,2,3)$ will have the same form offering comparison between different cutting methods. The precalculated $k_{s}$ values are available either in tables or graphically expressed, consider-


Fig. 1. Elements of cutting process
ably facilitating any further calculation. The use of specific cutting force presents the advantage to simplify cutting force prediction: the known data ( $b, h, b h=A_{0}$ ) have to be multiplied with the appropriate tabulated $k_{s}$ values.

The practical advantages need completion by some theoretical considerations.

The specific cutting force on a surface unit has a physical meaning only if the area concerned and the cutting force are coherent. Remind that the area is under force effect and the relationship between area and force can be expressed numerically.

The shear plane $A_{\Phi}$ as well as the tool rake face contacting the chip $A_{\gamma}$ are the main factors influencing force acting during the cutting process while the nominal cross section $A_{0}$ does not intervene. The value of $A_{0}$ can be expressed exactly and the resulting ratio is a good reference, but $A_{0}$ is of no practical use in finding the real cutting force.

It is evident from the linear force equation $F=A^{0} A_{0}+B^{0}$ that the increase of the chip cross section does not affect the component $B^{0}$. Namely $B^{0}$ has no role in generating the mean shear strength. If the function $k_{s}^{\prime \prime \prime}=A^{0}+$ $+\frac{B^{0}}{A_{0}}$ contained $A_{0} \rightarrow 0$, the resulting $k_{s}$ values would be extremely high and
had no physical meaning. Analyses made about $A_{0}=0$ raise the problem of the lower limit of validity for the equation.

Cutting is now discussed as a plane process, therefore results may simply be compared by referring the forces obtained from $\left(F_{1}=F \frac{b_{1}}{b}\right)[\mathrm{kp}]$ to the cross section $b_{1} h=A_{1}\left[\mathrm{~mm}^{2}\right]$ for unit length of edge. Without knowing $\Phi$, the first step will deliver the linear equations

$$
\begin{aligned}
F_{1} & =A A_{1}+B \text { for the main cutting force, } \\
F_{N 1} & =A_{N} A_{1}+B_{N} \text { for the normal force. }
\end{aligned}
$$



Fig. 2. Components of cutting force

For about similar cutting operations in nearly identical conditions of temperature, strain and strain rate, the value of $\Phi$ will be unaffected or nearly so, consequently the relationship between the nominal area $A_{1}$ and the shear plane $A_{\Phi 1}$, i.e. $A_{\Phi 1}=A_{1} / \sin \Phi$ will remain constant. Any change in $\Phi$ will impair the linear approximation. Essentially, $\Phi$ is decisive for the intervals of linear approximation.

## 2. Calculation of mean shear stress

The linear equation $F_{1}=A A_{1}+B$ is expressing the main cutting force. $A A_{1}$ is seen to be the only term which increases proportionally to $A_{1}$ and for unchanged also to $A_{\Phi 1}$. $\operatorname{Be} A_{1}^{\prime}$ the lowest limit of validity of the linear equation within the range of measured data it may be written (Fig. 3):

$$
\begin{equation*}
A\left(A_{1}-A_{1}^{\prime}\right)=\bar{\tau}_{\Phi} \frac{A_{1}-A_{1}^{\prime}}{\sin \Phi} \cdot \frac{\cos \psi}{\cos (\Phi+\psi)} \tag{7}
\end{equation*}
$$



Fig. 3. Calculation of main cutting force


Fig. 4. Scalar values of main cutting force and its components


Fig. 5. Vectors of cutting force


Fig. 7. Scalar values of difference vectors


Fig. 6. Vectors shifted to the origin


Fig. 8. Calculation of mean shear stress


Fig. 9. Calculation of difference vectors

Introducing the expression $\Omega=\frac{\cos \psi}{\cos (\Phi+\psi) \sin \Phi}$

$$
\begin{equation*}
A=\bar{\tau}_{\Phi} \frac{\cos \psi}{\cos (\Phi+\psi) \sin \Phi}=\bar{\tau}_{\phi} Q \tag{8}
\end{equation*}
$$

The mean shear strength $\bar{\tau}_{\Phi}=\frac{A}{Q}$.
while

$$
F_{\mathrm{l}}=\bar{\tau}_{\varphi} \Omega A_{1}+B
$$

In orthogonal cutting, the cutting force is determined from two measured components, mostly the main cutting force $F[\mathrm{kp}]$ and the normal force $F_{N}[\mathrm{kp}]$ perpendicular to the former. These are, naturally, the components most frequently discussed in literature. References on the resulting force $F_{R}$, its measure and direction, are scarcely found in literature. The fact that any change in direction of the resulting force has also to be considered, makes difficulties in linearization, except for components of a given direction.

To investigate this problem, Fig. 4 shows not only the curve describing the two components but also that of the resulting scalar value. Some cutting force vectors pertaining to the relevant $A_{1}$ values are also plotted (Fig. 5). Shifting the same vectors to the origin, the $F_{\mathrm{Ni}}$ values are plotted against $F_{1}$ (Fig. 6). Each $F_{1}-F_{N 1}$ group determines a point $F_{R_{1}^{1}}^{A}$. These points fit a curve of slope $\xi$, intersecting the axis $F_{N 1}$ at point $F_{R_{1}}^{B}$. In accordance with the linear equations of the components, the values $B$ and $B_{N}$ extrapolated to $A_{1}^{0}$ determine the vector $\bar{f}_{R_{1}^{1}}^{A 0}$. The difference vectors $\bar{f}_{R_{1}^{1}}^{A i}-\bar{f}_{R_{1}^{1}}^{A v}=f_{R_{1}}^{k_{i}}$ are proportionel to the corresponding $A_{1}^{i}$ values. Fig. 7 indicates the scalar values of the difference vectors by $A_{1}$, i.e. $f_{R_{3}}^{k}=R A_{1}$. Thus, the cutting force vector is obtained by adding the vector $\bar{f}_{R_{1}^{1}}^{A N}$ to $f_{K_{1}}^{h_{i}}$, the difference vector $R A_{1}$ of slope $\xi$. The mean shear stress is obtained from the variation of the difference vector.

The curve of scalar values of the difference vector in the $A_{1}-A_{N} A_{1}$ system (Fig. 8) is completed with the shear plane illustrated in physically true direction. The component of $R A_{1}$ in the shear plane is

$$
\begin{equation*}
F_{\Phi 1}=R A_{1} \cos (\Phi+\xi) \tag{9}
\end{equation*}
$$

its reference plane being $A_{1} / \sin \Phi$
thus

$$
\begin{equation*}
\bar{\tau}_{\Phi}=R \cos (\Phi+\xi) \sin \Phi \tag{10}
\end{equation*}
$$

where $\xi$ is a constant.

Fig. 9 idealizing the difference vectors clearly shows the length of the difference vectors to be

$$
\begin{equation*}
f_{R_{1}}^{k}=A_{1} \sqrt{A^{2}+A_{N}^{2}}=R A_{1} \tag{11}
\end{equation*}
$$

thus

$$
\begin{aligned}
R & =\sqrt{A^{2}+A_{N}^{2}} \\
\xi & =\operatorname{arctg} \frac{A_{N}}{A}
\end{aligned}
$$

furthermore
According to the equation

$$
\begin{equation*}
\bar{\tau}_{\Phi}=R \cos (\Phi+\xi) \sin \Phi=\sqrt{A^{2}+A_{N}^{2}} \cos \left(\operatorname{arctg} \frac{A_{N}}{A}+\Phi\right) \sin \Phi \tag{12}
\end{equation*}
$$

the factors determining the mean shear stress are the angle $\Phi$ of the shear plane and the constants of the components' equations.

## 3. Numerical determination of the mean shear stress on the basis of data by Thomsen, Lapsley and Grassi [1]

As stated by a number of authors [2,3,4] the relationship between undeformed chip thickness and cutting force components in the range $h<0.3 \mathrm{~mm}$ is a linear one. Let me quote some data from "Deformation work absorbed in metal cutting" by Thomsen, Lapsley and Grassi (Table I; $\gamma=25^{\circ}$ ). Working conditions: material Shelby tubing, $D=6 \mathrm{in}$, chip thickness 0.475 in , tool HSS, clearance angle $6^{\circ}, v=90 \mathrm{fpm}$, dry cutting.

Table I
Data by Thomsen, Lapley and Grassi [1]

| $\Phi^{\circ}$ | $\psi^{\circ}$ | $h(\mathrm{in})$ | $F(\mathrm{lb})$ | $F_{v}(\mathrm{bb})$ | $A_{1}\left(\mathrm{~mm}^{2}\right)$ | $F_{1}(\mathrm{kp})$ | $F_{M_{1}}(\mathrm{kp})$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |
| 20.9 | 25.0 | 0.0025 | 380 | 224 | 0.0635 | 14.29 | 8.42 |
| 21.5 | 27.0 | 0.0035 | 475 | 281 | 0.0889 | 17.86 | 10.57 |
| 24.0 | 26.0 | 0.0050 | 643 | 357 | 0.1270 | 24.18 | 13.42 |
| 20.1 | 26.0 | 0.0060 | 728 | 398 | 0.1524 | 27.37 | 14.96 |
| 22.4 | 27.5 | 0.0085 | 992 | 551 | 0.2159 | 37.30 | 20.72 |
|  |  |  |  |  |  |  |  |

In Table I the converted values $h[\mathrm{~mm}], F_{1}$ and $F_{N 1}[\mathrm{kp}]$ are also given. The paper referred to contains values for $\gamma=35^{\circ}, 40^{\circ}, 45^{\circ}$, too.

The constants calculated from the equations
and

$$
\begin{gathered}
F_{1}=A A_{1}+B \\
F_{\mathrm{N} 1}=A_{N} A_{1}+B_{N}
\end{gathered}
$$

as well as the standard deviation of the linear approximation are shown in Table II. The mean shear stress values and the data needed for their calculation are found in Table III.

Table II
Constants and standard deviation of linear force equations

| $\gamma^{\circ}$ | $A\left(\mathrm{k}_{\mathrm{T}} / \mathrm{mm}^{2}\right)$ | $B(\mathrm{kp})$ | s ${ }_{F}^{p} \%$ | $A_{N}\left(\mathrm{kp} / \mathrm{mm}^{2}\right)$ | $B_{N}(\mathrm{kp})$ | sf Nl \% |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | 151.15 | 4.62 | 0.93 | 79.41 | 3.33 | 1.85 |
| 35 | 106.49 | 2.56 | 1.86 | 32.92 | 1.82 | 2.45 |
| 40 | 99.87 | 2.47 | 1.41 | 20.23 | 3.16 | 3.16 |
| 45 | 87.18 | 3.20 | 1.25 | 12.09 | 1.88 | 2.75 |

Table III
Values calculated from the constants of linear equations

| $\gamma^{2}$ | $\Phi^{\nu}$ | $\xi^{\rho}$ | $(\Phi+\xi)^{\circ}$ | $R\left(\mathrm{kp} / \mathrm{mm}^{2}\right)$ | $\cos (\Phi+\xi)$ | $\sin \Phi$ | $\bar{\tau} \Phi\left(\mathrm{sp} / \mathrm{mm} \mathrm{m}^{2}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | 21.8 | 27.7 | 49.5 | 170.0 | 0.65 | 0.37 | 41.0 |
| 35 | 31.8 | 15.7 | 47.5 | 112.0 | 0.68 | 0.53 | 40.7 |
| 40 | 36.6 | 11.3 | 47.9 | 102.0 | 0.67 | 0.58 | 39.5 |
| 45 | 40.7 | 7.9 | 48.6 | 88.0 | 0.66 | 0.65 | 38.0 |

The value of $(\Phi+\xi)$ is seen to be nearly constant $\left(48.5^{\circ} \pm 1^{\circ}\right)$. If angle $\gamma$ increases by $20^{\circ}, \Phi$ will increase and $\xi$ decrease to the same extent. The angle $(\Phi+\xi)$ will rotate by as much as the increase of angle $\gamma$. For a growth by $20^{\circ}$ of angle $\gamma, R$ will be smaller by $48 \%, \bar{\tau}_{\Phi}$ by $7.5 \%$.

## Summary

Specific cutting forces calculated from known force equations have no physical meaning. Physically meaningful indices require consideration of coherent forces and areas of cut. Between their ranges of validity, linear force equations may deliver coherent force to area values. Their constants and the angle $\Phi$ of the shear plane yield the mean shear stress.

## References

1. Thomsen et al.: Deformation work absorbed by the work piece during metal cutting. Trans. of ASME. May 1953.
2. Strempel, H.: Schnitt- und Drangkraftverhalten bei Gegenlaufphasen. Fertigungstechnik und Betrieb 11, 675 (1964).
3. Rezek, Ö.: Examination of friction conditions at orthogonal cutting. Periodica Polytechnica. Mech. E. 14 449-456 (1970).
4. Richter, A.: Zerspanungshräfte beim Drehen im Bereich des Fließspans. Wiss. Zeitschr. TH Dresden 2, 5 (1952/53).

Dr. Ödön Rezek, Budapest XI, Stoczek u. 8-10, Hungary

