P Periodica Polytechnica Transportation Engineering

The Use of Weighted Adjacency Matrix for Searching Optimal Transportation Routes

https://doi.org/10.3311/PPtr.11171 Creative Commons Attribution ①

RESEARCH ARTICLE

Received 21 February 2017; accepted 11 July 2017

Karel Antos1*

Abstract

This article provides a new approach to searching solutions of the ship transport optimalization problems. It brings a new variant of one algorithm of searching for the Minimum Spanning Tree. The new element in the algorithm is that it uses the Weighted Adjacency Matrix. This Weighted Adjacency Matrix is suitable for searching for the Minimum Spanning *Tree (MST) of the graph. It shows how it could be used in cases* where weighted edges of the graph are given. This creates a new procedure of searching for the MST of the graph and completes previously known algorithms of searching for the MST. In the field of transportation it could be succesfully use solutions of optimizing transportation routes where sm costs are wanted. Proposed Weighted Adjacency Matrix c be used in similar issues in the field of the graph theory, when is show graphs with weighted edges are given. The on the attached example.

Keywords

graph theory, minimum spanne, tree, Josep, Fruskal, reverse, algorithm

¹Department of Informatics and Natural Sciences, Institute of Technology and Business in České Budějovice, Okružní 517/10, 30 01 České Budějovice, Czech Republic *Corresponding author, e-mail: antos.vst@mail.vstecb.cz

1 Introduction

One of the important aims shipping traffic is to find the ideal comb oing traffic tion of ites so as ility of all pl reduce costs to ensure the servi and of transport cop low as poss t is necessary to transport costs to the minimum. reach each hub and to red nd transport i s are shipping lanes. Hubs are

Great theory offers useful tool, for solving problems in this area for model this situation we create a connected weighted grap where vertices represent sea ports and the edges represent the rates between the ports through which ships transporting goods. In weight can edge between two vertices represents represents the near the ports.

beginning there is a situation where ships transport bods between hubs over many different routes and in different ways, but the transport links are inefficient and expensive as a vhole.

The task of our algorithm is now to optimize the connections between hubs, so that the cost of transport links between all ports were minimal with the condition that every port is reachable through traffic routes.

To search for optimal transport connection we can use the tool spanning tree from the graph theory. This tool is useful to optimize the connections between all hubs to be as simple as possible. Another tool is the minimum spanning tree, which ensures that this unique connection will be the least expensive. For searching the minimum spanning tree we offer here a new algorithm, which complements the previously known algorithms and demonstrates new and original approach.

2 Description of the MST issues

All graphs in this article are finite, simple and connected. The system of shipping traffic routes we can transform into the graph where vertices represent sea ports, edges represent transport routes and weights of edges represent the energy consumed to drive the boat between two ports. To model this situation we create a connected graph G = (V, E) with weighted edges. The optimal traffic connection of the system is represented by the spanning tree of the graph. And the problem of

the cheapest traffic system means that we must find the minimum spanning tree.

The spanning tree of a connected graph G is a subgraph G' which connects all vertices and which does not contain any cycles (Kleinberg and Tardos, 2006). The minimum spanning tree we denote T = (V, E'), where V' = V and E' is the set of n-1 edges of the minimum spanning tree, and it applies that $E' \subseteq E$. In the subsequent text we use the abbreviation MST (short for the Minimum Spanning Tree) (Jackson and Read, 2010). The sum of the weights of edges of MST is minimal.

For searching for the minimum spanning tree there are several obviously known algorithms which search for the MST in different ways. For example The Kruskal's algorithm, Prim's algorithm or Borůvka's algorithm are the generally known. In the article we use some principles of Prim's algorithm for searching the MST (Kruskal, 2004). But this article presents a new procedure for searching for the MST, which is Weighted Adjacency Matrix.

Let G = (V, E) be a connected, finite and non-oriented graph with positively weighted edges, where V is a set of n vertices and E is the set of m edges. The set of vertices V we denote $V = \{v_1, v_2, ..., v_n\}$ and the set of edges we denote E, where e_{ij} denotes the edge between vertices v_i and v_j , then it is $e_{ij} = \{v_i, v_j\} \in E$. $W(e_{ij})$ denotes the weight of the edge connecting vertices v_i and v_j , where $e_{ij} = \{v_i, v_j\} \in E$.

The spanning tree of a connected graph *G* is a subgraph which connects all vertices and which does not contain any cycles (Fredman and Willard, 1984). For this subgraph with holds that G' = (V', E'), where V' = V and E' = V'. Note that E' set contains n - 1 edges (Charge et al., 2011).

For subgraph G' = (V', E') where $graph G = put w(G') = \sum_{e \in E'} w(e)$. Because where s_{P} wire dree is a free with denote it T.

The spanning tree $T_1 = (E_1)$ of the grap G we call the minimum spanning the if for the spanning tree $T_2 = (V, E_2)$ of the graph G it has that $w(T_1) = (T_2)$.

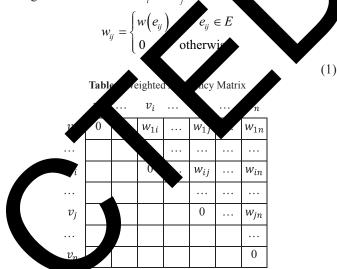
The minim spanning tree we de T = (V, E'), where V' = V and n-1 edges of the minimum spanning is the set $E' \subseteq E$. In the subsequent text we use tree, and plies 5Γ (short f he Minimum Spanning Tree). the abbrevia $E \rightarrow R$ (ie. evaluation of edges), efine t nctior ing tree is such a spanning tree for then the hinimum holds that the sum of the weights of edges of MST is which $\int = \sum_{e \in E'} w(e)$ is minimal.

In the following capture there is displayed a new algorithm when uses some new elements for searching the MST and adopts them its he of the previously mentioned, to the Prim's algorithm.

3 Weighted Adjacency Matrix

At first in the proposed algorithm we create a modified adjacency matrix, which we call "Weighted Adjacency Matrix". This matrix is similar to the Adjacency Matrix where in positions of elements of the matrix are either 1 or 0 if there is an edge between vertices v_i and v_j or not. In this modified Weighted Adjacency Matrix the positive number w_{ij} on the position of the element v_i and v_j indicates the weight of the edge connecting vertices v_i and v_j , if the edge between vertices v_i and v_j exists. A value of 0 indicates that there is no edge between vertices v_i and v_j (Goldberk, 1987).

Weighted Adjacency Matrix (Table 1) is thus a componential $W = n \times n$, where *n* denotes the number of vertices and the plue of the element at the position w_{ij} corresponds to the weight the edge between vertices v_i and v_i .



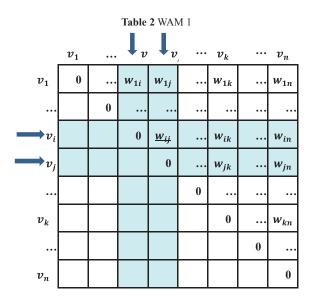
bted Adjacency Matrix is symmetric with respect to the main diagonal, the diagonal elements have a value of 0, the algorithm will only use the elements of the triangle above the main diagonal. The algorithm of searching for the MST works in the Weighted Adjacency Matrix and works with elements in the triangle above the main diagonal.

4 Algorithm procedure

Search through the elements of the matrix and find the one with the smallest positive value w_{ij} . Denote chosen matrix element in bold and underlined, then mark the rows v_i , v_j and columns v_i , v_j (Denote the columns and rows with arrows at the top of the table). If there is more than one element with the same smallest positive value, it is possible to choose arbitrary one of these. Then more than one MST exists.

Search again through the elements of the matrix and find another smallest positive element, search between elements in the marked rows and columns (Table 2). Chosen element denote in the matrix in bold and underlined. Let the new element be w_{jk} . According to the index position of the element mark the row v_k and column v_k . Rows and columns marked in the previous steps remain marked.

This step ensures the connection of the generated MST because the connecting edge has one of the indexes the same as the previous selected element, so this element connects to any of previously connected vertices.



Furthermore delete (ie. replace by the cross) all the elements in positions where newly marked row and column intersect with rows and columns previously marked. Here delete the element w_{ik} . This step prevents creating cycles.

Search again through the elements of the matrix and find another smallest positive element, search between elements in the marked rows and columns. Chosen element denote in the matrix in bold and underlined (Table 3). Let the new element be w_{1i} . According to the index position of the element want the row v_1 and column v_1 . Rows and columns marked in a previous steps remain marked. Furthermore delete all the elements in positions where newly marked row and column inter sect with rows and columns previously proceed. Here elete the elements w_{1i} and w_{1k} (Table 4).

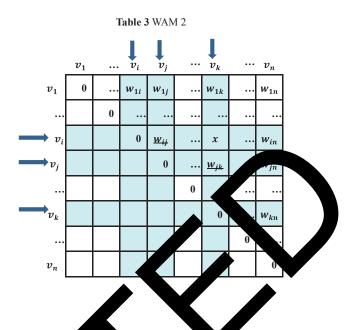
Suppose that our algorithm m

- If k = n 1, algorithm s ps, we have de all steps
- If k < n 1, we make (n 1)-th step analogy states and (n 1)-th step analogy states are also been as (n 1).

r Weighted Adjacency After we make the (n-1)-th step 1 Matrix (n-1)en elements are labe (in bold and underlined), the ot elements which were not chosen) are replaced by a cross. e sam me all rows and columns in our matrix are labeled (Ta Elements noted in the matrix in bold weights of edges of the MST. lues. ned a abeling mns of the selected element indirows ar ces v_i and v_j that the edge on this position concates th e values of all chosen elements gives the ie sum or veight of the MST.

5 Verification of the algorithm

 Continuity of generated MST is guaranteed by the fact that newly connected edge has one of the indices the same as the indices of previously selected elements (Kruskal, 2000). Therefore, it connects to one of the previously connected vertices.





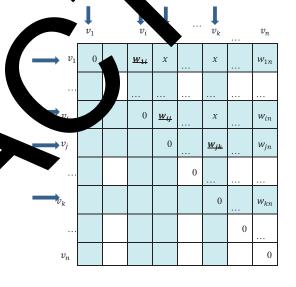
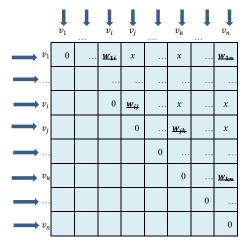


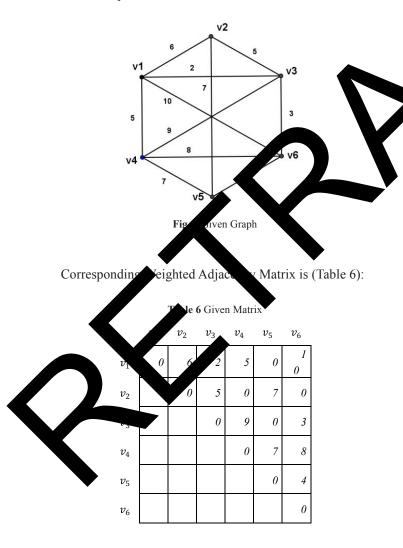
Table 5 Final Matrix



- 2. Avoiding the cycles is ensured by deleting all the elements in positions where newly marked row and column intersect with rows and columns previously marked (Cormen, et al., 2001).
- 3. The algorithm is a variant of the Prim's algorithm, with the difference that in the first step we do not begin by selecting the arbitrary initial vertex, but in our Weighted Adjacency Matrix we begin by selecting the edge with the smallest weight. From the second step our algorithm works analogously as in the Prim's algorithm (which has been proven, see (Harris et al., 2000)). This guarantees selection of the minimum spanning tree.

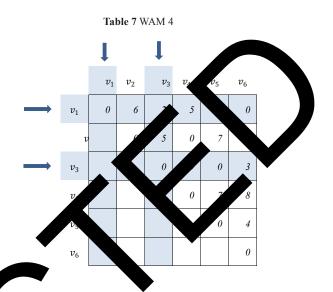
6 Demonstration of solved Example

Imagine the system of the sea transport routes. At first we transform the system of transport routes into the weighted graph (Fig. 1). There are 6 ports represented by 6 vertices of the graph $v_1, v_2, ..., v_6$, connections between the ports are represented by the edges in the graph and numbers belonging to the edges represent the costs of energy consumed to drive the boat between two ports.

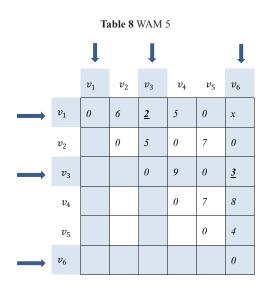


7 Steps of algorithm

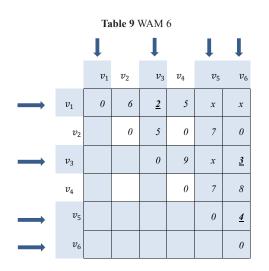
1. Search through the elements of the matrix and find the one with the smallest positive value $w_{13} = 2$. Denote chosen matrix element in bold and underlined, then mark the rows v_1 , v_3 and columns v_1 , v_3 (Table 7).



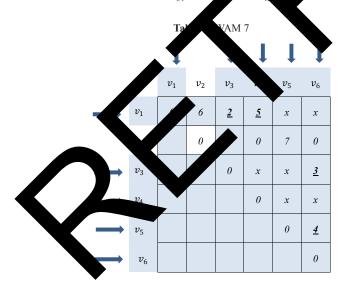
Search again through the elements of the matrix and find another smalled positive element $w_{36} = 3$, search between elements in the matrix of columns. Chosen eleted denotes in the matrix in bold and underlined. According to the index position of the element mark the $v_{10}v_{6}$ and column v_{6} . Rows and columns marked in the previous steps remain marked (Table 8). Furthermore we delete (ie. replace by the cross) all the elements in positions where newly marked row and column intersect with rows and columns previously marked. Here we delete the element w_{16} .



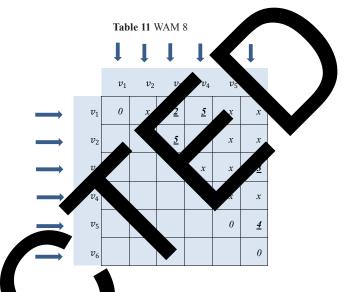
3. Search again through the elements of the matrix and find another smallest positive element $w_{56} = 4$, search between elements in the marked rows and columns. Chosen element denote in the matrix in bold and underlined. According to the index position of the element mark the row v_5 and column v_5 . Rows and columns marked in the previous steps remain marked. Furthermore delete all the elements in positions where newly marked row and column intersect with rows and columns previously marked. Here delete the elements, $w_{34} = x$, $w_{35} = x$ (Table 9).



4. Search again through the elements of the matrix and find another smallest positive element $w_{14} = 5$, search between elements in the marked rows and columns. Choser thement denote in the matrix in bold and underlined. Act aroing to the index position of the element mark the ro v_4 and column v_4 . Rows and columns marked in the previosteps remain marked. Furthermore deleter and element in positions where newly marked and and column intersect with rows and columns previously marked. Here delete the elements $w_{34} = x$, $w_{34} = x$.



5. Search again through the elements of the matrix and find another smallest positive element $w_{23} = 5$, search between elements in the marked rows and columns. Chosen element denotes in the matrix in bold and underlined. According to the index position of the element mark the row v_2 and column v_2 . Rows and columns marked in the previous steps remain marked. Furthermore delete all the elements in positions where newly marked row and column intersect with rows and columns previously marked. Here delete the elements $w_{12} = x$, $w_{24} = x$, $w_{25} = x$, $w_{26} = x$ (Table 11).



8 Televination of the algorithm

When we graphe has *n* vertices then the MST has n - 1 lises (Kleinberg and Tardos, 2006). At each step of the algorithm add to the gradually rising MST one edge, then gorithm makes n - 1 steps. In our example, the graph has 6 vertices, then the MST has 5 edges. That is the reason why algorithm makes 5 steps.

After the final step, all the elements in the Weighted Adjacency Matrix went through processing, ie. the edges chosen for the MST are denoted in the agreed way, i.e. here in bold and underlined, deleted edges are marked by symbol x.

At the same time, after the last step all the rows and columns of the matrix are marked with the arrows next to the rows and above columns.

9 Final graph of the MST is here

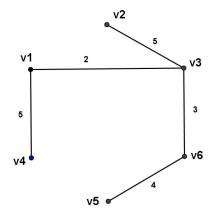


Fig. 2 Final Graph of the MST

Value of the final MST is:

$$\sum_{e \in E'} w(e) = (2+3+4+5+5) = 19.$$
⁽²⁾

10 Conclusion

This article describes the proposal of the algorithm for searching for the minimum spanning tree. The proposed algorithm is similar to the Prim's algorithm (Harris et al., 2000), which creates the minimum spanning tree as gradually growing set of edges of the MST. In this regard there is a compliance with Prim's algorithm. The Prim's algorithm starts with the arbitrary vertice. Here, however, the first element the algorithm starts with is the edge with the lowest weight (Jackson and Read, 2010).

The new tool here is the "Weighted Adjacency Matrix (abr. WAM)". It follows the principle of adjacency matrix known known in the graph theory, but in the positions of matrix elements there are values of weights of edges connecting the vertices. The vertices denote the rows and columns of the matrix.

The whole process of searching MST begins with choosing the smallest element of the matrix, representing the edge with the lowest weight. Gradually we add elements so that another new element has one index same as some of the elements that have been chosen in previous steps. This step guarantees the continuity of MST.

Elements which in denoted rows and columns are prochosen, must be removed because these edges would create ven. The entire process takes place in WAM, the original gr h is not needed.

Benefits of the proposed algorithm is the uncharching of MST by using WAM is efficient and fast according of my know edge the searching for the MST by using WAM is a constant and it can be assumed that the WAM build to use nor solving other similar problems in the grapher where weighed edges are given. Working of the algorithmer a syn on solved example.

The proposed algo ble for optimizing the ship .nm is transport because hip traffic routes can be е system of the into the Weighted A easibly transf ency Matrix which is graph with weighted edges. Solving clear repre tation of the probl ng for the minimum spanning tree goes f sea lustratively presented in the in this matr kly and ample

References

- Chazelle, B. (2000). A minimum spanning tree algorithm with inverseackermann type complexity. *Journal of the ACM*. 47(6), pp. 1028-1047. https://doi.org/10.1145/355541.355562
- Chong, K. W., Han, Y., Lam, T. W. (2001). Concurrent threads and optimal parallel minimum spanning trees algorithm. *Journal of the ACM*. 48(2), pp. 297-323.

https://doi.org/10.1145/375827.375847

- Cormen, T. H., Leiserson, C. E., Rivest, R. L, Stein, C. (2001) Introduction to Algorithms. 2nd Edition. MIT Press and Corraw-D. CBN 0262033844 9780262033848
- Fredman, M. L., Willard, D. E. (1993). Surpassing the information theor ic bound with fusion trees. *Journal of Computer of System Science* 47(3), pp. 424–436.

https://doi.org/10.1016/0022-000 3)90040-4

Fredman, M. L., Willard, D. E. (1990) trans-dichorations algorithment minimum spanning trees and showt paths *in transformation of Computer and System Sciences*. 48(3), pp. 33–55

https://doi.org/10/ 6/S0022-0000 80064-9

Goldberg, A. W. (1990) Scient Graph Algor was free equential and Parallel Computer and the Department of Electrical Engineering and Computer Science, MIT.

Harris, J. Martin, J. L., Hossh ander, M. J. (2000). Combinatorics and aph Theory. Springer, New 1

https://doi.org/10.1007/978-1-4757-4803-1

s://doi.org/10

on, T. S., Read, N. (10). Theory of minimum spanning trees. *Physical Review E*. 81, 0211

3/PhysRevE.81.021130

- Kleinbe, Tarder, (2006). Algorithm Design. Pearson Education, Inc., New York.
 - *I.B.* (1956). On the shortest spanning subtree of a graph and the tracking salesman problem. *Proceedings of the American Mathematical Society*. 7, pp. 48–50.

https://doi.org/10.1090/S0002-9939-1956-0078686-7

- Maren, M. (2008). Graph Algorithms (The Saga of Minimum Spanning Trees). PhD thesis, Charles University, Prague, Czech Republic. [Online]. Available from: http://mj.ucw.cz/papers/saga/ Accessed: 1st April 2017]
- Matousek J., Nesetril, J. (2009). Kapitoly z diskrétní matematiky. (The Chapters from discrete Mathematics.), 4th edition, Prague, Charles University in Prague. ISBN 978-80-246-1740-4 (in Czech).
- Pettie, S., Ramachandran, V. (2002). An optimal minimum spanning tree algorithm. *Journal of the ACM*. 49(1), pp. 16-34. https://doi.org/10.1145/505241.505243
- Prim, R. C. (1957). Shortest connection networks and some generalizations. *The Bell System Technical Journal*. 36(6), pp. 1389–1401. https://doi.org/10.1002/j.1538-7305.1957.tb01515.x