

# On dynamics of the track/vehicle system in presence of inhomogeneous rail supporting parameters

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## Abstract

We study the dynamics of the train/track system in case of an inhomogeneous longitudinal subgrade stiffness/damping distribution. Our model consists of a Bernoulli-Euler beam, fixed at infinity, laying on a viscoelastic Winkler foundation of continuously varying stiffness/damping parameters, and a damped oscillatory load moving along the beam at a constant velocity. In order to obtain an approximate, semianalytical solution we build up a new discretization method based on the approximation of the discretized stiffness/damping values by generalized functions. The approximate solutions tend to continuous functions represented in a closed-form, analytical fashion.

## Keywords

railway track dynamics · beam equation · inhomogeneous supporting field

## 1 Introduction

In our simple model we consider a viscoelastic Winkler foundation of continuously varying stiffness/damping parameters given by functions  $s_0 + s(x)$ ,  $k_0 + k(x)$ , a Bernoulli-Euler beam of parameters  $EI$ ,  $\rho A$  laying on the subgrade, and a load of weight  $G$  moving along the beam at a longitudinal velocity  $v$ , and vibrating dampedly at complex frequency  $w = \alpha + i\omega$ . In case  $\alpha = 0$  we have a harmonic load, while  $w = 0$  stands for the case of a constant load.

The motion of the system is governed by the Bernoulli-Euler beam equation

$$EI \frac{\partial^4 z}{\partial x^4} + \rho A \frac{\partial^2 z}{\partial t^2} + (k_0 + k(x)) \frac{\partial z}{\partial t} + (s_0 + s(x))z = G \exp(wt) \delta(x - vt), \quad (1)$$

where  $\delta$  stands for Dirac's unit impulse distribution, while continuous functions  $s$  and  $k$  vanish outside the finite interval  $[x_0, y_0]$ .

Eq. (1) satisfies boundary conditions

$$\lim_{|x| \rightarrow \infty} z(x, t) = 0 \quad (2)$$

at  $\pm\infty$ .

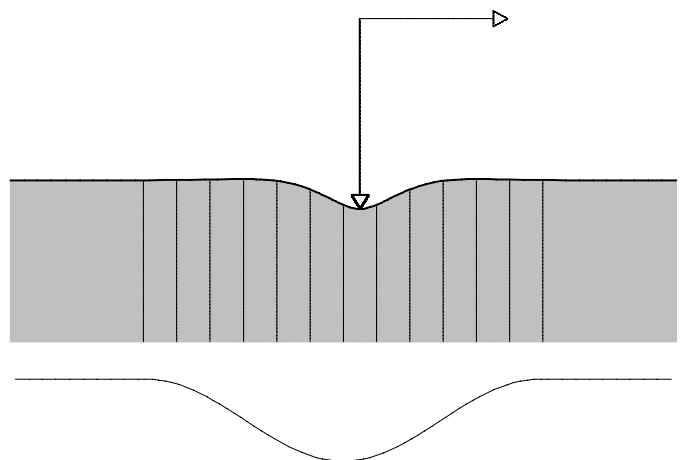


Fig. 1. System model

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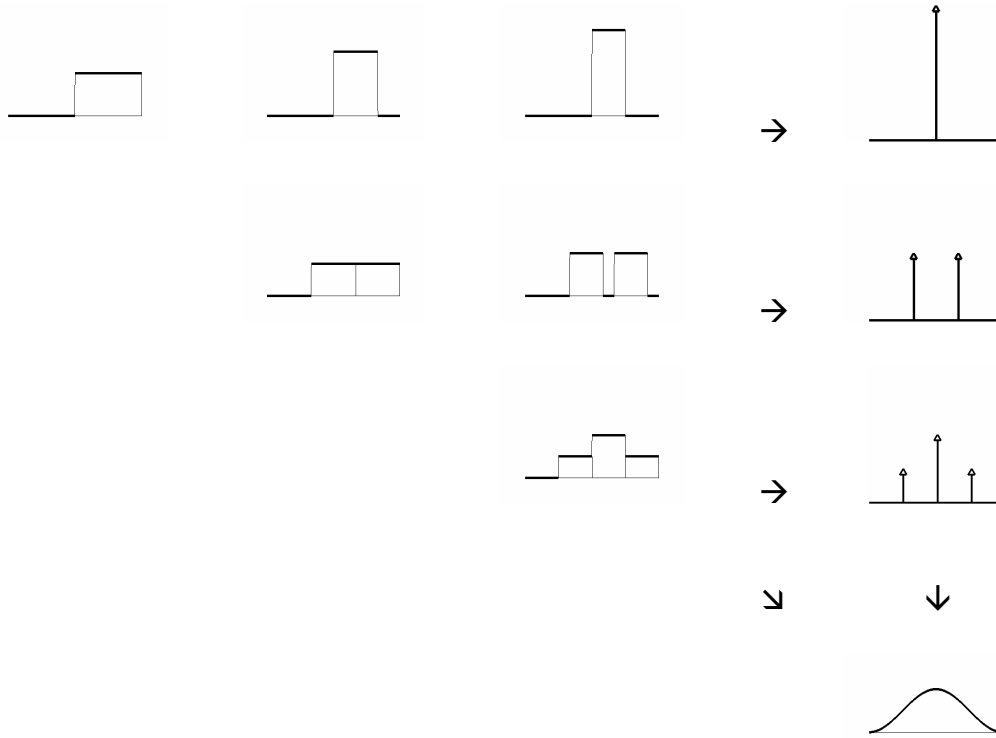


Fig. 2. The limits of the discretized function sequences

## 2 Approximate boundary problem

First we discretize parameter functions of the subgrade in the following way.

We build up step functions

$$s_{kn}(x) := \begin{cases} s(x_j) \frac{h}{k} & \text{if } x \in [x_j, x_j + \frac{hn}{k}), j = 0, 1, \dots, n-1, \\ 0 & \text{otherwise.} \end{cases}$$

by discretizing continuous function  $s(x)$  (or  $k(x)$ ), for  $k \geq n$ , where  $h := (y_0 - x_0)/n$  and  $x_j := x_0 + jh$ ,  $j = 0, 1, \dots, n$  hold.

In this case  $\lim_{n \rightarrow +\infty} s_{nn}(x) = s(x)$  is satisfied. For the limit, which is a generalized function, in case  $k \rightarrow +\infty$

$$s_n(x) := \lim_{k \rightarrow +\infty} s_{kn}(x) = \sum_{j=1}^n s(x_j) \delta(x - x_j) h$$

holds, and for its limit

$$\lim_{n \rightarrow +\infty} s_n(x) = \int_{x_0}^{y_0} s(y) \delta(x - y) dy = s(x)$$

is satisfied, hence we have the following commutative diagram:

$$\begin{array}{ccc} & k \rightarrow \infty & \\ S_{kn} & \rightarrow & S_n \\ & & \downarrow n \rightarrow \infty \\ k=n \rightarrow \infty & \searrow & S \end{array}$$

The different limits of discretized function sequences are illustrated in Fig. 2.

The beam equation discretized to  $n$  parts in case  $k \rightarrow +\infty$

has the form

$$EI \frac{\partial^4 u}{\partial x^4} + \rho A \frac{\partial^2 u}{\partial t^2} + k_0 \frac{\partial u}{\partial t} + s_0 u = G \exp(\omega t) \delta(x - vt) - \sum_{j=1}^n \left( s(x_j) u(x_j, t) + k(x_j) \frac{\partial}{\partial t} u(x_j, t) \right) h \delta(x - x_j). \quad (3)$$

Response to the first term is

$$G \sum_{i=1}^4 \frac{\sigma_i}{P'(\lambda_i)} \exp(\omega t + \lambda_i(x - vt)) H(\sigma_i(x - vt))$$

with characteristic polynomial

$$P(\lambda) = EI \lambda^4 + \rho A v^2 \lambda^2 - v(k_0 + 2\rho A \omega) \lambda + (s_0 + k_0 \omega + \rho A \omega^2) \quad (4)$$

and signs  $\sigma_i := -\text{sgn} \text{Re} \lambda_i$ ,  $P(\lambda_i) = 0$ ,  $i = 1, \dots, 4$ , see e.g. [1],[3].

The full response has the form  $u(x, t) = \sum_{i=1}^4 \exp(\omega t + \lambda_i(x - vt)) u_i(x)$ , and can be given in a recursive way as

$$\sum_{i=1}^4 \sigma_i \exp(\omega t + \lambda_i(x - vt)) \{GH(\sigma_i(x - vt))/P'(\lambda_i) -$$

$$h \sum_{j=1}^{n-1} c_i(x_j) u_i(x_j) H(\sigma_i(x - x_j))\}$$

with functions defined by

$$c_i(x) := \sigma_i \exp(\lambda_i x) \frac{s(x) + (\omega - \lambda_i v) k(x)}{4EI \lambda_i^3},$$

$$i = 1, 2, 3, 4, \quad (5)$$

cf. [2],[4].

### 3 Recurrence formulae

For  $Re\lambda_i < 0$  we have  $\sigma_i = 1$  and recursion

$$u_i(x_k) = \frac{G}{P'(\lambda_i)} H(x_k - vt) - h \sum_{j \leq k} c_i(x_j) u_i(x_j)$$

with solution

$$u_i(x_k) = \frac{G}{P'(\lambda_i)} H(x_k - vt) \prod_{j \leq k} \frac{1}{1 + c_i(x_j)h}$$

If  $n \rightarrow +\infty$  holds, then we obtain

$$\begin{aligned} \lim_{n \rightarrow +\infty} \prod_{x_j \leq x} (1 + c_i(x_j)h) &= \\ \lim_{n \rightarrow +\infty} \prod_{x_j \leq x} ((1 + c_i(x_j)h)^{1/(c_i(x_j)h)})^{c_i(x_j)h} &= \\ \exp \lim_{n \rightarrow +\infty} \sum_{x_j \leq x} c_i(x_j)h &= \exp \int_{x_0}^x c_i(y)dy. \end{aligned}$$

In the case  $Re\lambda_i > 0$  we have recurrence formula

$$u_i(x_k) = \frac{-G}{P'(\lambda_i)} H(vt - x_k) + h \sum_{j > k} c_i(x_j) u_i(x_j)$$

with solution

$$\begin{aligned} u_i(x) &= \frac{-G}{P'(\lambda_i)} H(vt - x) \prod_{x_j > x} (1 + c_i(x_j)h) \rightarrow \\ \frac{-G}{P'(\lambda_i)} H(vt - x) \exp \left( - \int_{y_0}^x c_i \right), & \quad n \rightarrow +\infty. \end{aligned}$$

Summarizing the results obtained above we get a finite closed-form integral formula for the continuously supported problem (1-2) in form

$$\begin{aligned} z(x, t) &= G \sum_{i=1}^4 \frac{\sigma_i}{P'(\lambda_i)} \\ \exp \left( wt + \lambda_i(x - vt) - \int_{l_i}^x c_i(y)dy \right) & H(\sigma_i(x - vt)) \quad (6) \end{aligned}$$

$$\text{with } l_i := \begin{cases} x_0 & \text{if } Re\lambda_i < 0, \\ y_0 & \text{if } Re\lambda_i > 0. \end{cases}$$

### 4 Numerical results

In the example, similar to that of [5], the parameters of the beam are  $EI = 6 \cdot 10^6 \text{ Nm}^2$ ,  $\rho A = 60 \text{ kg/m}$ . The weight of the constant load is  $G = 6.5 \cdot 10^4 \text{ N}$ , while its horizontal velocity is  $v = 40 \text{ m/s}$ . The parameters of the subgrade are given by constants  $s_0 = 9 \cdot 10^7 \text{ N/m}^2$ ,  $k_0 = 4.6 \cdot 10^4 \text{ Ns/m}^2$  and single sinusoidal waves

$$\begin{aligned} s(x) &= \begin{cases} (\cos(\frac{\pi x}{20 \text{ m}}) - 1) \cdot 10^7 \text{ N/m}^2, & \text{if } 0 \text{ m} \leq x \leq 40 \text{ m}, \\ 0 & \text{otherwise,} \end{cases} \\ k(x) &= \begin{cases} (\cos(\frac{\pi x}{20 \text{ m}}) - 1) \cdot 2500 \text{ Ns/m}^2, & \text{if } 0 \text{ m} \leq x \leq 40 \text{ m}, \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

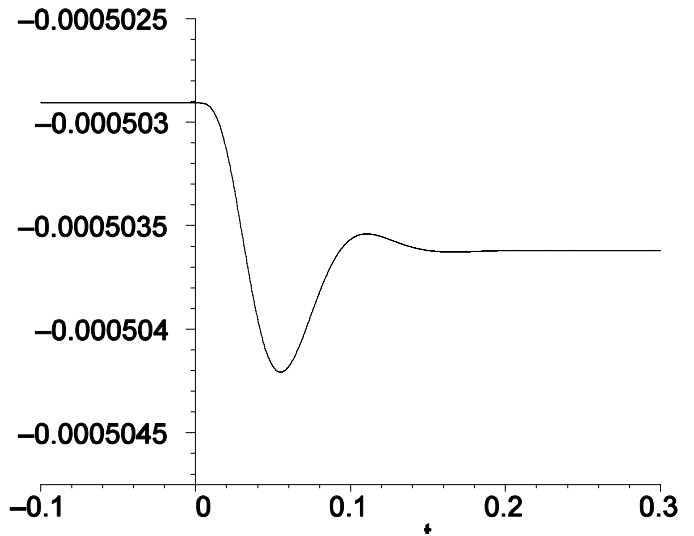


Fig. 3. The vertical position  $z(vt, t)$  of the load

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